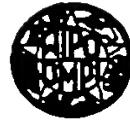


PCTWORLD INTELLECTUAL PROPERTY ORGANIZATION
International Bureau

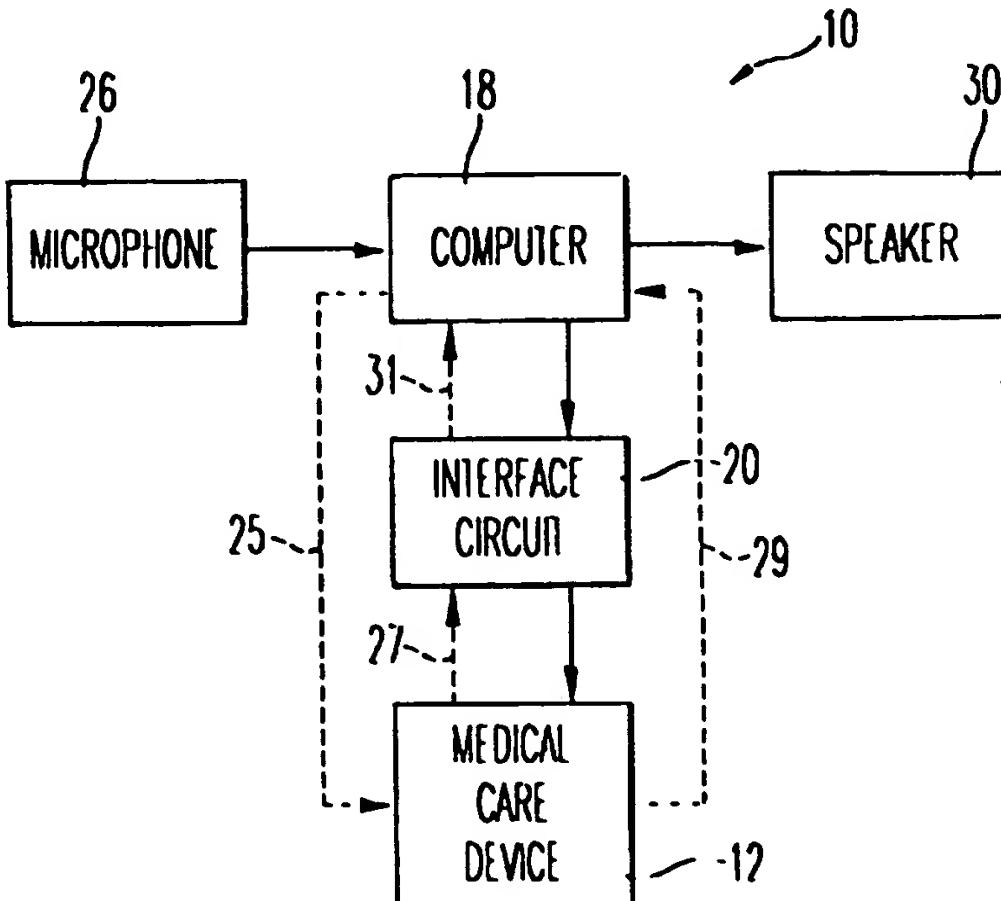
INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification 6 : A61B 19/00		A1	(11) International Publication Number: WO 97/15240
			(43) International Publication Date: 1 May 1997 (01.05.97)
(21) International Application Number:	PCT/US96/17320	(81) Designated States: AL, AM, AT, AT (Utility model), AU, AZ, BB, BG, BR, BY, CA, CH, CN, CZ, CZ (Utility model), DE, DE (Utility model), DK, DK (Utility model), EE, EE (Utility model), ES, FI, FI (Utility model), GB, GE, HU, IL, IS, JP, KE, KG, KP, KR, KZ, LK, LR, LS, LT, LU, LV, MD, MG, MK, MN, MW, MX, NO, NZ, PL, PT, RO, RU, SD, SE, SG, SI, SK, SK (Utility model), TJ, TM, TR, TT, UA, UG, UZ, VN, ARIPO patent (KE, LS, MW, SD, SZ, UG), Eurasian patent (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European patent (AT, BE, CH, DE, DK, ES, FI, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, ML, MR, NE, SN, TD, TG).	
(22) International Filing Date:	24 October 1996 (24.10.96)		
(30) Priority Data:			
60/006,107	25 October 1995 (25.10.95)	US	
08/708,015	30 August 1996 (30.08.96)	US	
(71) Applicant: JOHN HOPKINS UNIVERSITY [US/US]; 720 Rutland Avenue, Baltimore, MD 21205 (US).			
(72) Inventors: BRANT, Arthur, 6372 Joyce Ann Drive, Youngstown, OH 44511 (US). MANDELL, Kenneth, 4250 Blue Barrow Ride, Ellicott City, MD 21042 (US). RADER, R., Scott, 802 Leadenhall Street, Baltimore, MD 21239 (US). WALSH, Alexander, 13910 Cuba Road, Hunt Valley, MD 21030 (US). DeJUAN, Eugene, Jr., 13721 Poplar Hill Road, Phoenix, MD 21131 (US). GREENBERG, Robert, 2175 Bay Boulevard, Atlantic Beach, NY 11509 (US).			
(74) Agents: LONGANECKER, Stacey, J. et al.; Roylance, Abrams, Berdo & Goodman, L.L.P., Suite 315, 1225 Connecticut Avenue, N.W., Washington, DC 20036 (US).			

(54) Title: VOICE COMMAND AND CONTROL MEDICAL CARE SYSTEM

(57) Abstract

A voice command and control medical care system is provided which comprises a processor (18) having a continuous speech recognition capability. The processor (18) is programmed to process a user's conversational speech to identify valid commands therein and to generate control signals for operating medical equipment (12) such as surgical tools in accordance with the commands. The processor is programmed to generate audio messages (30) reporting status information when requested, and to generate confirmation messages and await acknowledgement before executing a command. The system is configurational to interface with and control via voice activation essentially any piece of medical equipment having instruments and control switches that can be controlled via electrical or electromagnetic signals.



FOR THE PURPOSES OF INFORMATION ONLY

Codes used to identify States party to the PCT on the front pages of pamphlets publishing international applications under the PCT.

AM	Armenia	GB	United Kingdom	MW	Malawi
AT	Austria	GE	Georgia	MX	Mexico
AU	Australia	GN	Guinea	NE	Niger
BB	Barbados	GR	Greece	NL	Netherlands
BE	Belgium	HU	Hungary	NO	Norway
BF	Burkina Faso	IE	Ireland	NZ	New Zealand
BG	Bulgaria	IT	Italy	PL	Poland
BJ	Benin	JP	Japan	PT	Portugal
BR	Brazil	KE	Kenya	RO	Romania
BY	Belarus	KG	Kyrgyzstan	RU	Russian Federation
CA	Canada	KP	Democratic People's Republic of Korea	SD	Sudan
CF	Central African Republic	KR	Republic of Korea	SE	Sweden
CG	Congo	KZ	Kazakhstan	SG	Singapore
CH	Switzerland	LI	Liechtenstein	SI	Slovenia
CI	Côte d'Ivoire	LK	Sri Lanka	SK	Slovakia
CM	Cameroon	LR	Liberia	SN	Senegal
CN	China	LT	Lithuania	SZ	Swaziland
CS	Czechoslovakia	LU	Luxembourg	TD	Chad
CZ	Czech Republic	LV	Latvia	TC	Togo
DE	Germany	MC	Monaco	TJ	Tajikistan
DK	Denmark	MD	Republic of Moldova	TT	Trinidad and Tobago
EE	Estonia	MG	Madagascar	UA	Ukraine
ES	Spain	ML	Mali	UG	Uganda
FI	Finland	MN	Mongolia	US	United States of America
FR	France	MR	Mauritania	UZ	Uzbekistan
GA	Gabon			VN	Viet Nam

VOICE COMMAND AND CONTROL MEDICAL
CARE SYSTEM

This application claims the benefit of U.S. Provisional Application No. 60/006,107, filed October 25, 1995.

5 A portion of the disclosure of this patent document contains material which is subject to copyright protection. The copyright owner has no objection to the facsimile reproduction by any one of the patent disclosure, as it appears in the Patent and Trademark Office patent files or records, but otherwise reserves all copyrights whatsoever.

10

Field of the Invention

The invention relates to a voice command and control system for controlling medical equipment.

Background of the Invention

5

A number of voice assisted machine control applications have been developed due to recent advancements in speech recognition software. Examples of these applications include input and storage of electronic patient records, assistance in clinical diagnosis, generation and manipulation of medical images, and manipulation of surgical devices such as microscopes.

10

15

20

Voice activated control of surgical instruments for vitreo-retinal surgery, for example, appears to be a good application for voice actuation technology. Intraocular surgery frequently requires simultaneous use of elaborate and sophisticated pieces of equipment by the surgeon, and coordination and integration of such equipment in an operating room with assistants and one or more nurses. A nurse is typically required to manipulate equipment controls in response to a surgeon's commands. Delays can occur when the nurse is busy setting up or adjusting other parameters when the surgeon's command is received. Delays associated with the human interface between a surgeon and a nurse can increase complexity of the surgery, particularly when conditions inside the patient's eye change rapidly and unexpectedly.

25

30

U.S. Patent No. 4,989,253 discloses a voice control system for moving and focusing a microscope. The system is disadvantageous, however, because it employs a discrete speech recognition algorithm. An operator must therefore give simple verbal commands, which are typically only one or two words, and speak them clearly and slowly. During procedures such as intraocular eye surgery, it is difficult to expect a surgeon to speak in the slow, halting manner required for accurate word identification using a discrete speech recognition algorithm.

5

U.S. Patent No. 5,303,148 discloses a voice activated image display controller which requires each operator to speak every command in order to create a stored user-specific pronunciation list. The controller compares received digitized audio signals with the list to determine if a spoken word is a valid command. The controller is disadvantageous because it requires operators to undergo time-consuming training in order to use it.

10

15

A need exists, therefore, for a voice command and control system for medical equipment which allows a surgeon to render voice commands using natural, conversational speech and which does not require the surgeon to participate in extensive training of the speech recognition engine. Further, a need exists for a voice command and control system which allows a surgeon to effectively handle volatile and quickly changing patient conditions (e.g., intraocular pressure), and to decrease surgery time without compromising the safety of the surgical procedure.

Summary of the Invention

20

25

In accordance with an aspect of the present invention, a voice command and control system is provided which can process audio signals from a microphone to identify an operator's verbal commands contained within conversational speech using speech recognition software. The commands are then converted to digital control signals which can be applied to a medical care device. The system is configured to continuously monitor the audio signals such that the operator does not have to speak in a slow, deliberate and unnatural manner.

30

In accordance with another aspect of the invention, the system is configured to automatically generate a request for confirmation of a command signal, and to await

acknowledgement from the operator before executing the command.

5

In accordance with yet another aspect of the invention, the system is configured to provide audible status data relating to a parameter or function of the medical care device in response to an operator's query command.

10

In accordance with still yet another aspect of the invention, the system is programmed to define functions and parameters of the medical care device and corresponding commands which are valid when that function or parameter is active, and to store them in files. The files facilitate the speech recognition process, as well as increase safety and efficiency with which the voice controlled medical care device is used.

15

20

In accordance with an embodiment of the present invention, a voice controlled medical care system is provided which comprises (1) a medical care device to be controlled in accordance with commands spoken by an operator, the spoken commands being selected from the group consisting of a single command word, a command phrase comprising a plurality of the command words, and a mixed phrase comprising at least one command word and at least one non-command word; (2) a microphone for transducing the spoken commands and generating corresponding audio output signals; (3) a processor comprising a first port connected to the microphone for receiving the audio output signals, the processor being programmable to substantially continuously monitor the first port for the audio output signals, to process the audio output signals to identify the command words therein, and to generate corresponding control signals for transmission to the medical care device; and (4) an interface circuit connected to the processor and the medical care device and operable to

25

30

provide the control signals from the processor to the medical care device.

Brief Description of the Drawings

5 These and other features and advantages of the present invention will be more readily apprehended from the following detailed description when read in connection with the appended drawings, which form a part of this original disclosure, and wherein:

10 Fig. 1 depicts a voice command and control medical care system constructed in accordance with an embodiment of the present invention and in use with an intraocular microsurgical system in an operating room;

15 Fig. 2 is a schematic block diagram of a voice command and control medical care system in accordance with an embodiment of the invention;

Figs. 3 and 4 depict an exemplary and known medical care device;

20 Fig. 5 is flowchart depicting the sequence of operations for processing an operator's verbal command to generate digital control signals for controlling a medical care device in accordance with an embodiment of the present invention;

25 Fig. 6 depicts a computer screen generated by a voice command and control medical care system in accordance with an embodiment of the present invention;

Figs. 7, 8, 9 and 10 illustrate computer screens generated by a voice command and control system in accordance with another embodiment of the present invention; and

30 Fig. 11 is a schematic block diagram of a hardware interface for connecting a computer with a medical care device in accordance with an embodiment of the present invention.

Detailed Description of the Preferred Embodiment

5 Fig. 1 depicts an operating room environment in which a voice command and control medical care system 10 is being used, in accordance with an embodiment of the present invention. The system 10 shall be described for illustrative purposes herein in connection with a Premiere® microsurgical system, which is commercially available from Storz Instrument Company, St. Louis, Missouri. The system 10 processes verbal commands to effect a desired change in a piece of equipment (e.g., a microsurgical system) via digital or analog circuit means. It is to be understood, however, that the system 10 can be used with other devices 10 besides the Premiere® microsurgical system in accordance with the present invention. These other devices can include, but are not limited to, a laser, a microscope, surgical tools such as remote-controlled scissors, medical imaging devices, devices for assisting patients such as electromechanical prosthetic and mobilization tools, devices for controlling medical care environments including room lighting and air quality, patient monitoring devices 15 such as sensors for patient vital signs, among others.

20

The Premiere® microsurgical system regulates speed, suction and other variables for intraocular surgical instruments which an ophthalmic surgeon holds in his or her hand during a surgical procedure. In accordance with the illustrated embodiment, a surgeon 14 or other operator of the voice command and control medical care system 10 can speak verbal commands into a headset 16 while performing surgery, as shown in Fig. 1. The system 10 comprises a computer 18, which is preferably a personal computer or a portable, laptop computer, and which is connected to the Premiere® microsurgical system 12 by an interface circuit 20 (Fig. 2). The system 10, therefore, eliminates the need to perform certain functions such as manipulating

5 instrument panel controls (indicated generally at 22) manually, thereby allowing the surgeon 14 and any other attending medical personnel 24 freedom to manipulate devices such as hand-held surgical tools and foot pedals and other operating room equipment. The system 10 can reduce burdens placed on a surgeon 14 and other medical attendants 24 during a surgical or other medical procedure, and can reduce the number of personnel required in the operating room. For example, a vitreo-retinal surgical suite is a complicated environment requiring several components of sophisticated medical equipment that are used simultaneously. A nurse is typically required to 10 manually press buttons on the Premiere® microsurgical system 12 in response to requests from the surgeon to, for example, increase the vitrectomy cut rate. In addition to the surgeon, two nurses are required throughout an 15 operation. The system 10 is cost effective in that it can transform this environment into an operating room requiring only one nurse and the surgeon. By eliminating the human 20 interface between the surgeon and the nurse to adjust the Premiere® microsurgical system 12, the voice command and control system 10 provides a faster and more accurate response which, in addition to the cost effectiveness of 25 reducing personnel, optimizes surgical outcome.

25 Fig. 2 is a schematic block diagram of the voice command and control medical care system 10. Operator voice commands are provided to a microphone 26 which is connected to the computer 18. The transduced audio signals received from the microphone 26 are processed in accordance with 30 speech recognition software. The system 10 preferably uses Listen® for Windows® version 2.0 by Verbex Voice Systems, Inc., Edison, New Jersey. The Listen® for Windows® software is user-independent to accommodate many surgeons or operators, without requiring extensive voice training

5

prior to use. The accuracy without training is approximately 80% to 90% for all users. The accuracy can be improved to approximately 100% when operators undergo training for less than one half hour to build an individual vocal profile. The refined operator specific grammar is saved in the memory of the computer or on magnetic disc or other storage device (e.g., a nonvolatile random access memory device) and can be utilized whenever that particular operator is using the system 10.

10

15

20

25

30

Listen® for Windows® provides a continuous versus discrete speech recognition algorithm. The software therefore allows an operator 14 to speak to the computer 18 in a natural and continuous manner, e.g., as a surgeon would normally speak to a nurse. Discrete algorithms for speech recognition are less effective than continuous speech recognition algorithms because they require users to speak more slowly and in a hesitant manner. Further, users typically speak only one or two words at a time. Surgeons may not be able to speak in the unnatural and discrete manner required for accurate recognition by discrete voice recognition algorithms during stressful situations encountered in an operation.

With continued reference to Fig. 2, the microphone 26 is preferably a unidirectional, noise canceling microphone Model P\N 42446-02-00 available from CTI Audio, Inc., Conneaut, Ohio. This microphone is preferred because it can specifically amplify the operator's commands only and is designed to reduce noise. The microphone 26 can be worn as a headset microphone 16, or can be permanently mounted on an operating room microscope 28 as shown in Fig. 1. The computer 18 is preferably an IBM Think Pad laptop computer because it is portable, has multimedia capabilities allowing it to receive microphone input signals, and has an Intel 486 DX33 processor which provides for efficient

execution of both speech recognition and digital conversion programs. The output from the microphone is connected to the microphone jack on the multimedia laptop computer 18.

As shown in Fig. 2, the computer 18 comprises or is connected to a speaker 30 to provide the surgeon with audible feedback and confirmation requests during the surgical procedure. The computer 18 provides control signals corresponding to an operator's verbal requests to a medical care device 12 via an interface circuit 20. In accordance with one embodiment of the present invention, the interface circuit 20 can be a hardware interface, as will be described in connection with Fig. 11. Alternatively, the computer 18 can provide control signals directly to the medical care device 12 via a serial or parallel port on the computer, as indicated by the phantom line 25. In accordance with other embodiments of the invention, the medical care device 12 can provide feedback signals to the interface circuit 20 or directly to the computer 18, as indicated by phantom lines 27 and 29, respectively, or the interface circuit can provide feedback signals to the computer 18, as indicated by phantom line 31.

With reference to Fig. 3, the Premiere® microsurgical system 12 controls a number of instruments that are placed inside the eye during vitreo-retinal surgery. These instruments can include, but are not limited to, a vitrectomy cutter 32, a fragmentation handpiece 34 and a needle 36. The microsurgical system 12 comprises a main console 38 having a display 40, a number of control buttons indicated generally at 42, and connectors for connecting an electrical line 46, an air line 48, an aspiration line 50, and an irrigation line 52, among others, to different surgical instruments. The microsurgical system 12 further comprises a remote controller 54 that can be connected to

the main console 38 via a single plug connector 56. The remote controller has a display 58 that is similar to the main console display 40.

As indicated in Fig. 4, the main console display 40 comprises function select switches 60, 62, 64, 66, 68, and 70 for operating the microsurgical system 12 in a number of modes, including Vitrectomy, Fragmentation, Scissors, Bipolar, Illumination and Intraocular Pressure (IOP) Control modes, respectively. The main console also has a number of input switches (e.g., ten input switches) 72 for controlling levels of variable functions such as aspiration and cut rate. The functions of these ten switches is determined by software used to control the microsurgical system 12. The functions of the switches changes with each screen 74 presentation.

With continued reference to Fig. 3, essentially any mode or feature can be selected, or any parameter level adjusted, using either the main console 38 or the remote controller 54. When a mode (e.g., Vitrectomy mode) is selected from either the console 38 or the remote controller 54, the mode is highlighted on the console screen, as indicated in Fig. 4, and flashes on the remote controller display. The operational modes of the microsurgical system 12 associated with normal posterior eye surgery will now be described for illustrative purposes. In the Vitrectomy mode, the microsurgical system 12 allows for vitreous cutting via the cutter 32 and for linear control over aspiration. In the Fragmentation mode, the microsurgical system 12 provides for phacofragmentation with linear control of aspiration for posterior segment procedures. The Scissors mode allows a surgeon to employ a pneumatically driven intraocular scissor instrument in single-cut, variable rate and proportional control modes. In single-cut control mode, scissors close rapidly when

5 actuated and remain closed until deactivated. In variable rate control mode, scissors open and close automatically at a cyclical rate established by a cut-rate display on display 40. In proportional control mode, scissors open and close in proportion to the level of actuation (e.g., the position of a foot pedal, or length or magnitude of an actuating control signal).

10 As stated previously, the main console 38 comprises push buttons or switches 42 (Fig. 3) for selecting operational modes and various parameters, and for increasing or decreasing the value of parameters. The remote controller 54 can facilitate activation of these buttons 42 via the computer 18. In the past, a surgeon mentally decides on a value for each parameter such as 15 bipolar power, cutting rate or maximum aspiration rate and conveys this selection verbally to a scrub nurse. The scrub nurse then interprets the verbal command and pushes the appropriate button on the main console 38 to select the desired parameter or to change the value of a given 20 parameter. The surgeon does not manually make the parameter or value change because he or she does not want to direct attention away from the microscope and the operation, while holding surgical instruments inside a patient's eye. The voice command and control of the 25 medical care system of the present invention is advantageous because it allows the surgeon to actuate appropriate buttons on the medical care device 12 without the nurse and by using only his voice, thereby reducing any delays in carrying out the verbal command as the command is interpreted and executed by a human being. This system 30 can therefore reduce personnel required in the operating room and the duration of the surgery.

The computer 18 preferably operates in a MicroSoft Windows® environment and has Listen® for Windows® software

5

10

15

20

25

30

stored in its digital memory. In accordance with an embodiment of the present invention, the computer 18 is also provided with a custom executable program, which is written, for example, using Visual C++ developmental software, to process command words identified by the speech recognition software and to manipulate the medical care device 12 accordingly. The custom software code is provided in Appendices A and B. The overall operation of the system will be described with reference to the flowchart in Fig. 5.

As shown in Fig. 5, the computer is programmed to essentially continuously monitor its microphone input for audio output signals from the microphone 26, which transduces utterances of the operator (block 80). Because the speech recognition software has a continuous speech recognition algorithm, the verbal commands of the operator need not be as discretely or precisely stated as with a discrete speech recognition algorithm. In other words, the surgeon can intermingle actual command words with unintended words such as hesitations (e.g., "uh").

With reference to block 82 of Fig. 5, the computer analyzes the audio output signals of the microphone 26 using the speech recognition software to identify command words therein. When the voice command and control medical care system 10 is being configured for use with a particular type of medical care device 12, the functional modes of that device 12 are identified and defined, along with parameters which can or cannot be changed within those modes and restrictions, if any, on changing to different modes. Commands are subsequently defined to allow a user to initiate a particular function of the device 12, change a parameter setting or functional mode. These commands are then stored in corresponding grammar files. Appendix A

contains several grammar files for using the system 10 with the Premiere® microsurgical device 12.

By way of example, Fig. 6 depicts a window screen on the monitor 40 of the computer 18. Against a Windows® environment background, a pop-up menu 84 is generated by the computer which lists available commands a surgeon can speak into the microphone while in the Vitrectomy mode selected and highlighted in Fig. 4. When any of these listed commands is spoken into the microphone, the computer 18 is programmed via the custom software program of the present invention to compare the audio output signal with the phrases listed in the grammar file labeled Posterior Vitrectomy Grammar in Appendix A. If the surgeon requests a change in the level of illumination (e.g., "Premiere®, set illumination high"), the computer 18 will ignore the command because it does not locate the word "illumination" in the Posterior Vitrectomy Grammar File, as indicated in blocks 90 and 91. Once a valid command is identified, the computer 18 is programmed to generate a pop-up menu corresponding to that command. This is illustrated in Figs. 7 and 8. The Premiere® microsurgical system 12 can also be used in an anterior versus posterior surgical mode to perform cataract surgery. The computer 18 is programmed to identify commands, generate screens and control medical instruments specific to the Premiere® microsurgical system when operating in the anterior surgical mode, as well as the posterior surgical mode.

Fig. 7 provides another example of a Vitrectomy mode screen. The box 86 on the left side of the screen provides status information for the selected instrument or mode (e.g., posterior vitrectomy). The computer 18 generates the status screen in accordance with data received from the medical care device 12. The computer 18 also generates the pop-up menu 88 on the right side of the screen which

corresponds to the current mode or instrument function in use by the operator. The pop-up menu 88 lists commands which can be used to operate an instrument in that particular mode, to change to another mode, to request status information regarding a system function such as aspiration rate, to set a parameter level such as "Premiere® set power high" or to issue a system command such as "stop listening". If the operator gives a verbal command such as "Premiere® go to fragmentation", the computer 18 is programmed to generate the screen depicted in Fig. 8.

The status screen 86 on the left hand side of the screen in Fig. 8 gives different status information from that of Fig. 7, that is, information pertaining to posterior fragmentation. In addition, the commands for operating an instrument, setting a parameter value, inquiring about the status of certain parameters such as power, as well as auxiliary commands, change from those of the pop-up menu for the posterior vitrectomy mode in Fig. 7. For example, the parameter values for setting power or switching the pulse on or off cannot be changed when in the Vitrectomy mode. Similarly, cut rate cannot be set in the Fragmentation mode. While in the Fragmentation mode, verbal commands given by the operator are processed by the computer 18 in accordance with the speech recognition software using the grammar file for fragmentation, which is also provided in Appendix A. Thus, the speech recognition software preferably accomplishes voice controlled navigation through the various modes and parameter value changes of the medical care device 12 during a surgical procedure using a library of context-dependent command definitions stored in various grammar files.

With continued reference to the flowchart in Fig. 5, once the computer 18 identifies a valid command in an audio

5

10

20

25

30

output signal from the microphone 26, the computer 18 is programmed to generate a confirmation message before executing the identified command, as shown in block 94, unless the command is a request for status information, as indicated in blocks 92 and 93. The confirmation messages are generated by the computer using prerecorded messages. Alternatively, synthesized speech messages can be generated by the computer 18 using appropriate software. The computer 18 is programmed to wait for acknowledgment from the operator before executing the command. Thus, the confirmation/acknowledgment feature of the system 10 increases the safety of the system, particularly in surgery, because the surgeon can cancel a verbal command, as described below.

The confirmation function of the present invention is illustrated in Fig. 9. The computer 18 generates a Confirm dialogue box 95. The pop-up menu 88 on the right hand side of Fig. 9 lists valid confirmation responses or commands which can be spoken by the operator and recognized by the computer 18. If the operator responds with "yes" or "OK", the computer 18 is programmed to execute the command, as shown in blocks 96 and 98. As shown in the status screens 86 in Figs. 8 and 10, the maximum power has been increased from 5% to 80%. The manner by which this is done will be described below in connection with Fig. 11. If the user responds with "no" or "cancel", the computer 18 is programmed to continue monitoring its microphone input for audio output signals from the microphone 26, as indicated by the negative branch of decision block 96. With reference to decision block 100, if the operator speaks the command "stop listening", the computer 18 ceases to identify commands, if any, in the surgeon's conversation via speech recognition until it is commanded to resume listening, as indicated in blocks 101 and 102.

The manner in which commands are executed by computer 18 will now be described. As stated previously, when the system 10 is to be used with a particular medical care device 12, the modes of operation and possibilities for affecting changes to different parameters throughout the modes is defined (e.g., using grammar files). The method by which modes are selected and parameter values are changed within the medical care unit 12 is also analyzed. In the case of the remote controller 54 of the Premiere® microsurgical system, it was determined that pushing any of thirty buttons on the controller could be simulated electronically by shorting together various pairs of 16 wires contained within the controller 54. To enable the computer 18 to control the remote controller 54, a hardware interface 103 was designed and fabricated as shown in Fig. 11. The hardware interface 103 was placed in a black box connected to a parallel port of the computer 18 by a standard printer cable, and connected to the Premiere® remote controller 54 by a 16-pin ribbon cable. The buttons 42 on the Premiere® microsurgical system are essentially soft keys which are programmed to have multiple functions, depending on the mode in which the microsurgical system 12 is operating when a valid command is identified in the audio output signals from microphone 26. For example, one of the input switches 72 in Fig. 4 can be depressed one time in the Scissor mode to increase scissor cut rate by 30%. The same button can be depressed one time in the Phacofragmentation mode to increase ultrasound power by 1%. Each command for a particular function is assigned a digital code which is stored in the digital memory of the computer 18. The codes can be used to affect a change to a parameter value, instrument setting or change an operational mode (e.g., selecting a different instrument).

5

10

In accordance with the illustrated embodiment of the present invention, the computer 18 is programmed to generate an 8-bit binary number corresponding to the command to be executed by the medical care device 12. The least significant bits (LSB) D0 through D3 and the most significant bits (MSB) D4 through D7 are provided to decoders 104 and 106, respectively. The decoders are connected to the inputs of four quad bi-lateral switches 108, 110, 112 and 114 via NAND gates on four quad 2-input NAND gate components 116, 118, 120 and 122, respectively. As shown in Fig. 11, each switch 108, 110, 112 and 114 has four outputs connected to the 16-pin ribbon cable and four outputs which are connected to ground.

15

20

25

30

By way of example, if a verbal command is given to set cut rate high while in the Vitrectomy mode, the computer 18 is programmed in accordance with the invention to map the command to an appropriate digital code. The code can correspond to a signal for operating one of the sixteen switches corresponding to outputs P0 through P16, for example. When activated, the switch allows an electrical signal to be applied to one of the sixteen internal wires in the controller 54 for simulating the activation of a push button on the main console 38. For example, if the button for increasing cut rate on the main console can be activated remotely by shorting together the fourth and eighth wires of the sixteen internal wires of the remote controller 54 via their corresponding switches 110 and 112, the computer 18 can output 0100B and 1000B at its parallel port. Accordingly, all of the outputs of the decoder 104 are high, except for pin number 4, which is set low. Similarly, all of the outputs of the decoder 106 are high, except for output number 8, which is set low. Each NAND gate receives a high value from the decoder outputs, except for pin numbers 4 and 8 on decoders 104 and 106,

5

respectively. The NAND gates produce a low value at the input of their corresponding switches, resulting in the switches staying open. However, switches corresponding to pins P4 and P8 of decoders 110 and 112, respectively, close since their corresponding NAND gates have one high and one low input, thus the internal wires of the controller 52 connected to pins P4 and P8 receive an electrical signal to emulate the pushing of a button on the main console 38.

10

15

20

25

30

It is to be understood that the number of buttons on a device 12 and the number of possible functions is arbitrary. For example, the computer 18 can be programmed to output digital signals in accordance with a matrix such that activating combinations of switches can effect different functions of the medical care device 12. In addition to providing data on a parallel port, the computer 18 can generate serial output signals which can be decoded by an interface circuit or the device 12 itself to affect desired parameter and mode changes, or other functions requested verbally by the operator. The control signals generated by the computer 18 to execute the operator's commands can be output via a parallel or serial port, can be conducted along an electrical wire or other communication link such as optical fiber. In addition, wireless communication can be used between the computer 18 and the device 12 to be controlled, such as ultrasonic signals, infrared signals, radio frequency signals or other electromagnetic signals.

The degree to which the parameters are changed can also be implemented in a number of different ways in accordance with various embodiments of the present invention. In the illustrated embodiment (Fig. 11), the closing of one of the switches corresponding to lines P0 through P15 simulates activation of a push button on the main console 38. The degree of change in the parameter

variable requested by the operator is programmed and stored in the digital memory of the computer 18. Changes to parameter values are incremented such that each time a manual console button is depressed (i.e., one of the switches P0 through P15 is activated), the parameter increases or decreases from its current state by a predetermined amount. For example, if the computer 18 identifies the command "Premiere® set power high", the computer 18 is programmed to generate a control signal at the parallel port which closes appropriate switches P0 through P15 to simulate a single depression of a control button to take the medical care device 12 to the next power level, which could be an increase of 1% or 10%. Alternatively, the rate at which parameters are incremented or decremented can be done continuously, as opposed to discretely.

In addition to discrete or incremental control, the amount by which parameters can be changed can also be implemented via proportional and derivative control. For example, a parameter can increased or decreased in value in proportion to the duration of the signal being sent to the medical care device by the computer 18 or interface circuit 20. Further, feedback data can be provided to the computer 18 or other processor (e.g., a processor in the interface circuit) from the medical care device 12 for monitoring purposes. The control signal is continuously applied, or increased or decreased in magnitude, until the parameter reaches a desired threshold or another condition in the program code has been satisfied. The change in parameter value can be accomplished numerically. For example, the operator can state "Microscope, increase power thirty percent" or "Microscope, increase power three zero percent" or "three, 'oh' percent". Using the speech recognition software, the computer 18 can identify the desired level or

value of a parameter from a verbal command, and then determine the amount of change required based on the current value of the parameter. The computer 18 subsequently generates and transmits one or more control signals to the medical care device 12 in order to manipulate the instrument or control button thereon and automatically jump to the desired level. Alternatively, the computer 18 can generate control signals to continuously or discretely increase or decrease the current parameter level of the instrument or control button to achieve the desired parameter level.

The interface between the computer 18 and the medical care device 12 can be implemented a number of ways such as a separate digital circuit (e.g., the circuit depicted in Fig. 11), or as components on a peripheral board inserted into a slot in a personal computer. The interface circuit can be implemented using digital or analog components or both. Further, the interface between the computer 18 and the medical care device 12 can be implemented completely using software run by the computer 18. In accordance with the present invention, the system 10 can be used to interface with essentially any type of variable input or output device that can be switched or actuated by an electrical or electromagnetic signal.

As stated previously, the system 10 can be used to control a number of different devices such as medical imaging devices, surgical instruments, and environmental control equipment in operating rooms, patients' rooms and laboratories. The device to be controlled is analyzed to ascertain those functions and tools that are to be voice actuated. A vocabulary of commands is defined to control each function or tool while the tool or function is active. The tool or function-specific commands are stored in a file (e.g., a grammar file) that is accessed by the computer

when processing an output signal from a microphone. The
5 file for a particular function or tool can be defined to
restrict the initiation of certain functional modes, the
use of certain tools or the amount a parameter can be
changed while that function or tool is active. When
executing a command in a file, the computer 18 facilitates
10 the initiation of another mode by deactivating the
instrument in current use and activating relevant
parameters in the new mode. The computer 18 can be
programmed via the content of the files and the order with
15 which the files and their corresponding screens (e.g., the
Posterior Vitrectomy Grammar file and the active screen
depicted in Fig. 7) are generated to anticipate commands
(i.e., to more efficiently process audio signals to
identify valid commands therein), as well as to guide
operator command choices, in accordance with an optimal
20 sequence for using a medical care device 12 or performing
a particular procedure such as intraocular surgery. The
degree to which parameters can be changed, and the manner
in which the device 12 is manipulated to affect the desired
25 change, is defined and appropriate control signals are
stored for subsequent retrieval or generation and
transmission to the device 12.

The system 10 is advantageous for medical procedures
25 such as intraocular surgery, for example, because
parameters such as IOP may need to be adjusted quickly and
unexpectedly during surgery. Unfortunately, the scrub
nurse, who typically manipulates control buttons on medical
care equipment, can be too busy setting up and adjusting
30 other instrumentation to quickly respond to a new command,
resulting in a delay in changing the parameter as needed.
This can reduce the response time of the surgeon to
changing conditions inside the eye and hence adversely
affect the outcome of the surgery. Using the system 10 of

the present invention allows changes to be made in chosen parameters directly by the surgeon, while allowing him or her to continue holding surgical instruments inside the eye. Further, the surgeon does not have to direct attention away from the patient and the microscope view to ascertain the value of a parameter. Following a query command, the computer 18 automatically generates a status report, using pre-recorded or synthesized messages and pronunciations of numerical values, which is broadcast over the speaker 30 (Fig. 2). The above-described features increase the safety of the medical procedure being performed using the voice controlled medical care system 10 of the present invention.

While certain advantageous embodiments have been chosen to illustrate the invention, it will be understood by those skilled in the art that various changes and modifications can be made herein without departing from the scope of the invention as defined in the appended claims.

- 22A -

APPENDIX A

```
; ;** START OF LISTEN.INI UPDATES **  
; ; [EXECUTE]  
Premier = C:\MSVC\BIN\PREMIER\PREMIER.EXE  
; ;**END OF LISTEN.INI UPDATES **  
; -----Speech Interface File-----  
#application "Premier" ; Application Name  
#include "setup.inc" ; Required Listen include file  
#include "prompt.inc" ; Required Listen include file  
#vocabulary "Premier" ; Vocabulary Name  
; -----  
  
; -----Grammar Common Section-----  
; ;COMMON.VSN - Listen 2.0 Common User Interface  
; -----  
  
#list *END  
#description " "  
end "end"  
exit "end"  
#end_list  
  
#list *DIGIT  
#description "Any digit from 0 to 9"  
0  
1  
2  
3  
4  
5  
6  
7  
8  
9  
#end_list  
  
#list *DIGIT-0H  
#description "Any digit, including oh(0)"  
oh "0"  
0  
1  
2  
3  
4  
5  
6  
7  
8  
9  
#end_list  
  
#list *DIGIT1-9
```

- 22B -

```
#description "Any digit from 1 to 9"
1
2
3
4
5
6
7
8
9
#end_list

#list $DIGIT1-8
#description "Any digit from 1 to 8"
1
2
3
4
5
6
7
8
#end_list

#list $DIGIT1-7
#description "Any digit from 1 to 7"
1
2
3
4
5
6
7
#end_list

#list $DIGIT1-6
#description "Any digit from 1 to 6"
1
2
3
4
5
6
#end_list

#list $DIGIT1-5
#description "Any digit from 1 to 5"
1
2
3
4
5
#end_list

#list $DIGIT1-4
#description "Any digit from 1 to 4"
```

- 22C -

```
1
2
3
4
#end list

#list #DIGIT1-3
#description "Any digit from 1 to 3"
1
2
3
#end_list

#list #DIGIT1-2
#description "Only the digits 1 or 2"
1
2
#end_list

#list #ZERO
#description "Either 0 or oh"
oh "0"
0
#end_list

#list #1-2DIGITS,,,1,2
#description "A series of 1 to 2 digits, including oh(0)"
oh "0"
0
1
2
3
4
5
6
7
8
9
#end_list

#list #1-3DIGITS,,,1,3
#description "A series of 1 to 3 digits, including oh(0)"
oh "0"
0
1
2
3
4
5
6
7
8
9
#end_list

#list #1-4DIGITS,,,1,4
```

- 22D -

```
#description "A series of 1 to 4 digits, including oh(0)"
  oh "0"
  0
  1
  2
  3
  4
  5
  6
  7
  8
  9
#end_list

#list #1-5DIGITS,,,1,5
#description "A series of 1 to 5 digits, including oh(0)"
  oh "0"
  1
  2
  3
  4
  5
  6
  7
  8
  9
#end_list

#list #1-6DIGITS,,,1,6
#description "A series of 1 to 6 digits, including oh(0)"
  oh "0"
  1
  2
  3
  4
  5
  6
  7
  8
  9
#end_list

#list #1-NDIGITS,,,*
#description "A series of any number of digits, including oh(0)"
  oh "0"
  0
  1
  2
  3
  4
  5
  6
  7
  8
  9
#end_list
```

- 22E -

```
#list *0-NDIGITS,,,'
#description "A series of any number of digits, including oh(0), all
optional"
    oh "0"
    0
    1
    2
    3
    4
    5
    6
    7
    8
    9
#end_list

#list *0-DIGIT-OH,,,0,1
#description "Any digit, including oh(0), all optional"
    oh "0"
    1
    2
    3
    4
    5
    6
    7
    8
    9
#end_list

#list *DIRECTION1-9,\NO_MOD_ALL
#description "Any digit from 1 to 9, used with the move command"
    1
    2
    3
    4
    5
    6
    7
    8
    9
#end_list

#list *3DIGITS-DT1\NO_MOD_ALL,,3,3
#description "Three digits, without oh(0), used for Digit Training."
    1
    2
    3
    4
    5
    6
    7
    8
    9
#end_list
```

- 22F -

```
#list *3DIGITS-DT2,\NO_MOD_ALL,,3,3
#description "Three digits, without 0(zero), used for Digit Training."
    oh "0"
    1
    2
    3
    4
    5
    6
    7
    8
    9
#end list

#list *NEGATIVE,,,0,1
#list_phrase modify negative word list
    negative "-"
    minus "--"
#end_list

#list *SWITCH_TO_LIST,\NO_MOD_ALL
#list_phrase modify switch to list
#description "The SWITCH_TO_LIST can only be modified from within the Listen Command Editors by selecting the 'Switch to list...' command, under the 'Edit' menu
    "program manager"
    "task list"
#include "switchto.inc"
#end_list

: -----
: Vocabulary level Host response templates and translations
: -----
```

```
#host_response
#translations
    #initiator ""
    #separator ""
    #terminator ""

#templates
    move up 1 > "<UP>"
    move up 2 > "<UP><UP>"
    move up 3 > "<UP><UP><UP>"
    move up 4 > "<UP><UP><UP><UP>"
    move up 5 > "<UP><UP><UP><UP><UP>"
    move up 6 > "<UP><UP><UP><UP><UP><UP>"
    move up 7 > "<UP><UP><UP><UP><UP><UP><UP>"
    move up 8 > "<UP><UP><UP><UP><UP><UP><UP><UP>"
    move up 9 > "<UP><UP><UP><UP><UP><UP><UP><UP><UP>"
    move down 1 > "<DOWN>"
    move down 2 > "<DOWN><DOWN>"
    move down 3 > "<DOWN><DOWN><DOWN>"
    move down 4 > "<DOWN><DOWN><DOWN><DOWN>"
    move down 5 > "<DOWN><DOWN><DOWN><DOWN><DOWN>"
```

```
move down 6 > "<DOWN><DOWN><DOWN><DOWN><DOWN><DOWN>"  
move down 7 > "<DOWN><DOWN><DOWN><DOWN><DOWN><DOWN><DOWN>"  
move down 8 > "<DOWN><DOWN><DOWN><DOWN><DOWN><DOWN><DOWN><DOWN>"  
move down 9 > "<DOWN><DOWN><DOWN><DOWN><DOWN><DOWN><DOWN><DOWN><DOWN>"  
move left 1 > "<LEFT>"  
move left 2 > "<LEFT><LEFT>"  
move left 3 > "<LEFT><LEFT><LEFT>"  
move left 4 > "<LEFT><LEFT><LEFT><LEFT>"  
move left 5 > "<LEFT><LEFT><LEFT><LEFT><LEFT>"  
move left 6 > "<LEFT><LEFT><LEFT><LEFT><LEFT><LEFT>"  
move left 7 > "<LEFT><LEFT><LEFT><LEFT><LEFT><LEFT><LEFT>"  
move left 8 > "<LEFT><LEFT><LEFT><LEFT><LEFT><LEFT><LEFT><LEFT>"  
move left 9 > "<LEFT><LEFT><LEFT><LEFT><LEFT><LEFT><LEFT><LEFT><LEFT>"  
move right 1 > "<RIGHT>"  
move right 2 > "<RIGHT><RIGHT>"  
move right 3 > "<RIGHT><RIGHT><RIGHT>"  
move right 4 > "<RIGHT><RIGHT><RIGHT><RIGHT>"  
move right 5 > "<RIGHT><RIGHT><RIGHT><RIGHT><RIGHT>"  
move right 6 > "<RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT>"  
move right 7 > "<RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT>"  
move right 8 > "<RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT>"  
move right 9 > "<RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT><RIGHT>"  
  
#control_response  
sample noise >\RECALIBRATE  
  
#grammar "Top/Menu"  
#context  
    "CONTEXT= PREMIER.EXE,*,*"  
#end_context  
#phrase !SHOW_RUN_MENU_0,\INACTIVE,1  
    #spoken show run menu  
    #response "<ALT+R>"  
#end_phrase  
    #phrase !RUN_ANTERIOR_1  
        #spoken run anterior  
        #response "<ALT+R>A"  
#end_phrase  
    #phrase !RUN_POSTERIOR_2  
        #spoken run posterior  
        #response "<ALT+R>P"  
#end_phrase  
  
#phrase !SELECT_MENU_ITEM_ADD2MENU_3,\INACTIVE,1  
#spoken select menu item  
#response "<ENTER>"  
#end_phrase  
  
#phrase !HIDE_MENU_ADD2MENU_4,\INACTIVE,1  
    #spoken hide menu  
    #response "<ESC><ESC>"  
#end_phrase  
  
#phrase !SWITCH_TO_SWITCH_TO_LIST_ADD2MENU_5,\NO_MOD_RESPONSE|\IN  
    #spoken switch to &SWITCH_TO_LIST  
    #response "$E" &SWITCH_TO_LIST "$"
```

```
#end_phrase

#phrase !BEGIN_PHRASE_TRAINING_PLEASE_ADD2MENU_6, \NO_MOD_RESPONSE
    #spoken begin phrase training please
    #response "$WS"
#end_phrase

#phrase !BEGIN_ADVANCED_TRAINING_PLEASE_ADD2MENU_7, \NO_MOD_RESPONSE
    #spoken begin advanced training please
    #response "$TS"
#end_phrase

#phrase !MOVE_UP_DIRECTION1-9_ADD2MENU_8, \INACTIVE, 1
    #spoken move up #DIRECTION1-9
#end_phrase

#phrase !MOVE_DOWN_DIRECTION1-9_ADD2MENU_9, \INACTIVE, 1
    #spoken move down #DIRECTION1-9
#end_phrase

#phrase !MOVE_LEFT_DIRECTION1-9_ADD2MENU_10, \INACTIVE, 1
    #spoken move left #DIRECTION1 9
#end_phrase

#phrase !MOVE_RIGHT_DIRECTION1-9_ADD2MENU_11, \INACTIVE, 1
    #spoken move right #DIRECTION1 9
#end_phrase

#phrase !NEXT_FIELD_ADD2MENU_12, \INACTIVE, 1
    #spoken next field
    #response "<TAB>"
#end_phrase

#phrase !PREVIOUS_FIELD_ADD2MENU_13, \INACTIVE, 1
    #spoken previous field
    #response "<SHIFT+TAB>"
#end_phrase

#phrase !CLOSE_WINDOW_PLEASE_ADD2MENU_14, \INACTIVE, 1
    #spoken close window please
    #response "<ALT+P4>"
#end_phrase

#phrase !MAXIMIZE_WINDOW_ADD2MENU_15, \INACTIVE, 1
    #spoken maximize window
    #response "<ALT+SPACE>x"
#end_phrase

#phrase !MINIMIZE_WINDOW_ADD2MENU_16, \INACTIVE, 1
    #spoken minimize window
    #response "<ALT+SPACE>n"
#end_phrase

#phrase !RESTORE_WINDOW_ADD2MENU_17, \INACTIVE, 1
    #spoken restore window
    #response "<ALT+SPACE>r"
#end_phrase
```

- 221 -

```
#phrase !SAMPLE_NOISE_ADD2MENU_18, \NO_MOD_ALL, 1
    #spoken sample noise
    #response ""
#end_phrase

#phrase !SHOW_PHRASE_WINDOW_ADD2MENU_19, \NO_MOD_RESPONSE|INACTIVE, 1
    #spoken show phrase window
    #response "$H$"
#end_phrase

#phrase !HIDE_PHRASE_WINDOW_ADD2MENU_20, \NO_MOD_RESPONSE|INACTIVE, 1
    #spoken hide phrase window
    #response "$h$"
#end_phrase

#phrase !SHOW_RECOGNIZED_TEXT_ADD2MENU_21, \NO_MOD_RESPONSE|\\INACTIVE, 1
    #spoken show recognized text
    #response "$RS"
#end_phrase

#phrase !HIDE RECOGNIZED_TEXT_ADD2MENU_22, \NO_MOD_RESPONSE|\\INACTIVE, 1
    #spoken hide recognized text
    #response "$r$"
#end_phrase

#phrase !RECORD_VOICE_ADD2MENU_23, \NO_MOD_RESPONSE|\\INACTIVE, 1
    #spoken record voice macro
    #response "$SS"
#end_phrase

#phrase !STOP_RECORDING_ADD2MENU_24, \NO_MOD_RESPONSE|\\INACTIVE, 1
    #spoken stop recording voice macro
    #response "$s$"
#end_phrase

#phrase !PLAYBACK_ADD2MENU_25, \NO_MOD_RESPONSE|\\INACTIVE, 1
    #spoken playback voice macro
    #response "$MS"
#end_phrase

#phrase !STOP_LISTENING_ADD2MENU_26, \NO_MOD_RESPONSE
    #spoken stop listening
    #response "$I$"
#end_phrase

#main_structure
#end_structure

#end_grammar
```

```
;; -----
;;          Premier - Untitled Grammar
;; -----
```

- 22J -

```
#grammar "Premier- Untitled"

#context
"CONTEXT=*,#32770,Premier - Untitled"
#end_context

#phrase !SAMPLE_NOISE_DIALOG_BOX_D0003_041,\NO_MOD_ALL,1
#spoken sample noise
#response
#end_phrase
#phrase !STOP_LISTENING_PROGRAM_MANAGER_334_467,\NO_MOD_RESPONSE,1
#spoken stop listening
#response "$I$"
#end_phrase
#phrase !RUN_POSTERIOR
#spoken run posterior
#response "<ALT+R> p"
#end_phrase
#phrase !RUN_ANTERIOR
#spoken run anterior
#response "<ALT+R>a"
#end_phrase

#main_structure
#end_structure

#end_grammar
```

```
;; -----
;; Confirm Grammar
;; -----


#grammar "Confirm"

#context
"CONTEXT=*,#32770,Confirm"
#end_context

#phrase !NO_169
#spoken no
#response "\e"
#end_phrase
#phrase !CANCEL_724
#spoken cancel
#response "\e"
#end_phrase
#phrase !YES_041
#spoken yes
#response "\r"
#end_phrase
#phrase !OK_041
#spoken oh kay
```

- 22K -

```
#response "\r"
#end_phrase

#main_structure
#end_structure

#end_grammar

;; -----
;; Dialog Box Grammar
;; -----


#grammar "Dialog Box"

#context
  "CONTEXT=*,#32770,*"
#end_context

#phrase !TOGGLE_CHECKBOX_DIALOG_BOX_103
  #spoken toggle checkbox
  #response "<SPACE>"
#end_phrase

#phrase !CANCEL_DIALOG_BOX_104
  #spoken cancel
  #response "<ESC>"
#end_phrase

#phrase !YES_DIALOG_BOX_105
  #spoken yes
  #response "y"
#end_phrase

#phrase !NO_DIALOG_BOX_106
  #spoken no
  #response "n"
#end_phrase

#phrase !OH_KAY_DIALOG_BOX_107
  #spoken oh kay
  #response "<ENTER>"
#end_phrase

#phrase !NEXT_FIELD_DIALOG_BOX_108
  #spoken next field
  #response "<TAB>"
#end_phrase

#phrase !MOVE_UP_DIRECTION1-9_DIALOG_BOX_109,\NO_MOD_ALL
  #spoken move up $DIRECTION1-9
#end_phrase

#phrase !MOVE_DOWN_DIRECTION1-9_DIALOG_BOX_110,\NO_MOD_ALL
  #spoken move down $DIRECTION1-9
```

- 22L -

```
#end_phrase

#phrase !MOVE_LEFT_DIRECTION1-9_DIALOG_BOX_111,\NO_MOD_ALL
  #spoken move left #DIRECTION1-9
#end_phrase

#phrase !MOVE_RIGHT_DIRECTION1-9_DIALOG_BOX_112,\NO_MOD_ALL
  #spoken move right #DIRECTION1-9
#end_phrase

#phrase !SAMPLE_NOISE_DIALOG_BOX_113,\NO_MOD_ALL
  #spoken sample noise
  #response ""
#end_phrase

#phrase !STOP_LISTENING_DIALOG_BOX_114,\NO_MOD_RESPONSE
  #spoken stop listening
  #response "^$I$"
#end_phrase

#phrase !SHOW_PHRASE_WINDOW_DIALOG_BOX_115,\NO_MOD_RESPONSE
  #spoken show phrase window
  #response "$H$"
#end_phrase

#phrase !HIDE_PHRASE_WINDOW_DIALOG_BOX_116,\NO_MOD_RESPONSE
  #spoken hide phrase window
  #response "$h$"
#end_phrase

#phrase !SHOW_RECOGNIZED_TEXT_DIALOG_BOX_117,\NO_MOD_RESPONSE
  #spoken show recognized text
  #response "$R$"
#end_phrase

#phrase !HIDE_RECOGNIZED_TEXT_DIALOG_BOX_118,\NO_MOD_RESPONSE
  #spoken hide recognized text
  #response "$r$"
#end_phrase

#phrase !TRAIN_PHRASES_DIALOG_BOX_119,\NO_MOD_RESPONSE
  #spoken begin phrase training please
  #response "$W$"
#end_phrase

#phrase !TRAIN_ADVANCED_DIALOG_BOX_120,\NO_MOD_RESPONSE
  #spoken begin advanced training please
  #response "$T$"
#end_phrase

#phrase !RECORD_VOICE_DIALOG_BOX_121,\NO_MOD_RESPONSE
  #spoken record voice macro
  #response "$S$"
#end_phrase

#phrase !STOP_RECORDING_DIALOG_BOX_122,\NO_MOD_RESPONSE
  #spoken stop recording voice macro
```

- 22M -

```
#response "$S$"
#end_phrase

#phrase !PLAYBACK_DIALOG_BOX_123, \NO_MOD_RESPONSE
    #spoken playback voice macro
    #response "$M$"
#end_phrase

#main_structure
#end_structure

#end_grammar

; -----
;      Anterior Vitrectomy Grammar
; -----


#grammar "Anterior Vitrectomy"

#context
"CONTEXT=", #32770, Anterior Vitrectomy"
#end_context
#phrase !PREMIER_GO_TO_I_A_467_169_358_500
    #spoken premier go to IA
    #response "premier goto IA\r"
#end_phrase
#phrase "PREMIER_END_VITRECTOMY_334_724_962_467"
    #spoken premier tEND vitrectomy
    #response "premier \"tEND\" vitrectomy\r"
#end_phrase
#phrase !PREMIER_GO_TO_VITRECTOMY_478_464_334
    #spoken premier go to phaco
    #response "premier goto phaco\r"
#end_phrase
#phrase !PREMIER_SET_CUTRATE_LOW_467_D0000
    #spoken premier set cut rate low
    #response "premier set cutrate low\r"
#end_phrase
#phrase !PREMIER_SET_CUTRATE_HIGH_467_D0000
    #spoken premier set cut rate high
    #response "premier set cutrate high\r"
#end_phrase
#phrase !PREMIER_SET_ASPIRATION_LOW_334_D0000
    #spoken premier set aspiration low
    #response "premier set aspiration low\r"
#end_phrase
#phrase !PREMIER_SET_ASPIRATION_HIGH_334_D0000
    #spoken premier set aspiration high
    #response "premier set aspiration high\r"
#end_phrase
#phrase !PREMIER_REPORT_ASPIRATION_467
    #spoken premier report aspiration
    #response "premier report aspiration\r"
```

- 22N -

```

#end_phrase
#phrase !PREMIER_REPORT_CUTRATE_467
  #spoken premier report cut rate
  #response "premier report cut rate\r"
#end_phrase

#phrase !SAMPLE_NOISE_DIALOG_BOX_D0000,\NO_MOD_ALL
  #spoken sample noise
  #response ""
#end_phrase

#phrase !STOP_LISTENING_DIALOG_BOX_D0000,\NO_MOD_RESPONSE,1
  #spoken stop listening
  #response "$IS"
#end_phrase

main_structure
end_structure

end_grammar

; -----
;           Posterior Vitrectomy Grammar
; -----


:grammar "Posterior Vitrectomy"

:context
'CONTEXT=*,#32770,Posterior Vitrectomy"
#end_context

#phrase !STOP_LISTENING_PROGRAM_MANAGER_500,\NO_MOD_RESPONSE
  #spoken stop listening
  #response "$IS"
#end_phrase

#phrase !PREMIER_REPORT_GAS_041
  #spoken premier report gas
  #response "premier report gas\r"
#end_phrase

phrase !PREMIER_SET_BIPOLAR_HIGH_478
  #spoken premier set bipolar high
  #response "premier set bipolar high\r"
#end_phrase

#phrase !PREMIER_SET_BIPOLAR_LOW_358
  #spoken premier set bipolar low
  #response "premier set bipolar low\r"
#end_phrase

#phrase !PREMIER_REPORT_BIPOLAR_705
  #spoken premier report bipolar
  #response "premier report bipolar\r"
#end_phrase

```

- 220 -

```
#phrase !PREMIER_GAS_ON_962
    #spoken premier gas on
    #response "premier gas on\r"
#end_phrase
#phrase !PREMIER_GAS_OFF_464
    #spoken premier gas off
    #response "premier gas off\r"
#end_phrase
#phrase !PREMIER_REPORT_ASPIRATION_467_041
    #spoken premier report aspiration
    #response "premier report aspiration\r"
#end_phrase
#phrase !PREMIER_REPORT_CUTRATE_467_467
    #spoken premier report cut rate
    #response "premier report cut rate\r"
#end_phrase
#phrase !PREMIER_SET_CUTRATE_HIGH_467_D0000_334
    #spoken premier set cut rate high
    #response "premier set cutrate high\r"
#end_phrase
#phrase !PREMIER_END_VITRECTOMY_334_724_962_467_169
    #spoken premier END vitrectomy
    #response "premier \"END\" vitrectomy\r"
#end_phrase
#phrase !PREMIER_GO_TO_PHACO_D0000_724
    #spoken premier go to scissors
    #response "premier goto scissors\r"
#end_phrase
#phrase !PREMIER_GO_TO_PHACO_D0000_478
    #spoken premier go to fragmentation
    #response "premier goto fragmentation\r"
#end_phrase
#phrase !PREMIER_SET_CUTRATE_LOW_467_D0001
    #spoken premier set cut rate low
    #response "premier set cutrate low\r"
#end_phrase
#phrase !PREMIER_SET_ASPIRATION_LOW_334_D0001
    #spoken premier set aspiration low
    #response "premier set aspiration low\r"
#end_phrase
#phrase !PREMIER_SET_ASPIRATION_HIGH_334_D0001
    #spoken premier set aspiration high
    #response "premier set aspiration high\r"
#end_phrase

#phrase !SAMPLE_NOISE_DIALOG_BOX_D0001\NO_MOD_ALL
    #spoken sample noise
    #response
#end_phrase

#main_structure
#end_structure
```

- 22P -

```
#end_grammar

;;
-----  
,,          Post Main Grammar  
;;

#grammar "Post Main"

#context
"CONTEXT=*,#32770,Posterior Main Menu"
#end_context

#phrase !STOP_LISTENING_PROGRAM_MANAGER_334,\NO_MOD_RESPONSE,1
    #spoken stop listening
    #response "$IS"
#end_phrase
#phrase !PREMIER_GO_TO_PHACO_041_500
    #spoken premier go to fragmentation
    #response "premier goto fragmentation\r"
#end_phrase
#phrase !PREMIER_GO_TO_1_A_467_169
    #spoken premier go to scissors
    #response "premier goto scissors\r"
#end_phrase
#phrase !PREMIER_END_VITRECTOMY_334_724
    #spoken premier $END posterior
    #response "premier \"$END\" program\r"
#end_phrase
#phrase !PREMIER_GO_TO_VITRECTOMY_478
    #spoken premier go to vitrectomy
    #response "premier goto vitrectomy\r"
#end_phrase

#phrase !SAMPLE_NOISE_DIALOG_BOX_D0003,\NO_MOD_ALL
    #spoken sample noise
    #response ""
#end_phrase

#main_structure
#end_structure

#end_grammar
```

```
;;
-----  
,,          Ant Main Grammar  
;;
-----
```

- 22Q -

```
#grammar "Ant Main"

#context
"CONTEXT=*,#32770,Anterior Main Menu"
#end_context

#phrase !PREMIER_GO_TO_PHACO_041_500_D0000
    #spoken premier go to phaco
    #response "premier goto phaco\r"
#end_phrase
#phrase !PREMIER_GO_TO_I_A_467_169_D0000
    #spoken premier go to IA
    #response "premier goto IA"
#end_phrase
#phrase !PREMIER_END_VITRECTOMY_334_724_D0000
    #spoken premier END anterior
    #response "premier \"$END\" program\r"
#end_phrase
#phrase !PREMIER_GO_TO_VITRECTOMY_478_D0000
    #spoken premier go to vitrectomy
    #response "premier goto vitrectomy\r"
#end_phrase

#phrase !SAMPLE_NOISE_DIALOG_BOX_D0004,\NO_MOD_ALL
    #spoken sample noise
    #response ""
#end_phrase

#phrase !STOP_LISTENING_DIALOG_BOX_D0004,\NO_MOD_RESPONSE,1
    #spoken stop listening
    #response "$IS"
#end_phrase

#main_structure
#end_structure

#end_grammar

;; -----
;;          Phaco Grammar
;; -----


#grammar "Phaco"

#context
```

- 22R -

```
"CONTEXT=*,#32770,Phaco"
#end_context

#phrase !PREMIER_SET_PULSE_RATE_OFF_041
    #spoken premier set pulse rate off
    #response "premier set pulserate off\r"
#end_phrase
#phrase !PREMIER_SET_PULSE_RATE_LOW_041
    #spoken premier set pulse rate low
    #response "premier set pulserate low\r"
#end_phrase
#phrase !PREMIER_REPORT_MIN_PHACO_041
    #spoken premier report min phaco
    #response "premier report min phaco\r"
#end_phrase
#phrase !PREMIER_REPORT_MAX_PHACO_467
    #spoken premier report max phaco
    #response "premier report max phaco\r"
#end_phrase
#phrase !PREMIER_REPORT_PULSERAIE_334
    #spoken premier report pulse rate
    #response "premier report pulse rate\r"
#end_phrase
#phrase !PREMIER_REPORT_ASPIRATION_500
    #spoken premier report aspiration
    #response "premier report aspiration\r"
#end_phrase
#phrase !PREMIER_SET_PULSE_RATE_HIGH_491
    #spoken premier set pulse rate high
    #response "premier set pulserate high\r"
#end_phrase
#phrase !PREMIER_GO_TO_1_A_467_169_358
    #spoken premier go to IA
    #response "premier goto IA"
#end_phrase
#phrase !PREMIER_END_VITRECTOMY_334_724_962
    #spoken premier END phaco
    #response "premier END phaco\r"
#end_phrase
#phrase !PREMIER_GO_TO_VITRECTOMY_478_464
    #spoken premier go to vitrectomy
    #response "premier goto vitrectomy\r"
#end_phrase
#phrase !PREMIER_SET_MAX_PHACO_LOW_705
    #spoken premier set max phaco low
    #response "premier set maxphaco low\r"
#end_phrase
#phrase !PREMIER_SET_MAX_PHACO_HIGH_145
    #spoken premier set max phaco high
    #response "premier set maxphaco high\r"
#end_phrase
#phrase !PREMIER_SET_MIN_PHACO_HIGH_281
    #spoken premier set min phaco high
    #response "premier set minphaco high\r"
#end_phrase
```

- 22S -

```
#phrase !PREMIER_SET_ASPIRATION_LOW_827
    #spoken premier set aspiration low
    #response "premier set aspiration low\r"
#end_phrase
#phrase !PREMIER_SET_CUTRATE_LOW_467_D0003
    #spoken premier set min phaco low
    #response "premier set minphaco low\r"
#end_phrase
#phrase !PREMIER_SET_ASPIRATION_HIGH_334_D0003
    #spoken premier set aspiration high
    #response "premier set aspiration high\r"
#end_phrase

#phrase !SAMPLE_NOISE_DIALOG_BOX_D0005,\NO_MOO_ALL
    #spoken sample noise
    #response ""
#end_phrase

#phrase !STOP_LISTENING_DIALOG_BOX_D0005,\NO_MOD_RESPONSE,1
    #spoken stop listening
    #response "$IS"
#end_phrase
```

```
#main_structure
#end_structure

#end_grammar
```

```
;; -----
;;          Irr/Asp Grammar
;; -----
#grammar "IA"

#context
"CONTEXT=*,#32770,Irrigation-Aspiration"
#end_context

#phrase !PREMIER_GO_TO_PHACO
    #spoken premier go to phaco
    #response "premier goto phaco\r"
#end_phrase
#phrase !PREMIER_END_VITRECTOMY_334_724_436
    #spoken premier &END IA
    #response "premier "&END" IA\r"
```

- 22T -

```
#end_phrase
#phrase !PREMIER_GO_TO_VITRECTOMY_478_391
    #spoken premier go to vitrectomy
    #response "premier goto vitrectomy\r"
#end_phrase

#phrase !SAMPLE_NOISE_DIALOG_BOX_D0006,\NO_MOD_ALL
    #spoken sample noise
    #response ""
#end _phrase

#phrase !STOP_LISTENING_DIALOG_BOX_D0006,\NO_MOD_RESPONSE,1
    #spoken stop listening
    #response "$I$"
#end_phrase

#main_structure
#end_structure

#end_grammar

;; -----
;;          Scissors Grammar
;; -----
#grammar "Scissors"

#context
"CONTEXT=*,#32770,Scissors"
#end_context

#phrase !STOP_LISTENING_PROGRAM_MANAGER_467,\NO_MOD_RESPONSE,1
    #spoken stop listening
    #response "$I$"
#end_phrase
#phrase !PREMIER_SET_CUTRATE_HIGH_467_D0000_334_041
    #spoken premier set cut rate high
    #response "premier set cutrate high\r"
#end_phrase
#phrase !PREMIER_SET_CUTRATE_LOW_467_D0001_467
    #spoken premier set cut rate low
    #response "premier set cutrate low\r"
#end_phrase
#phrase !PREMIER_REPORT_CUT_RATE_724
    #spoken premier report cut rate
    #response "premier report cut rate\r"
#end_phrase
```

- 22U -

```
#phrase !PREMIER_SET_BIPOLAR_HIGH_478_D0000
    #spoken premier set bipolar high
    #response "premier set bipolar high\r"
#end_phrase
#phrase !PREMIER_SET_BIPOLAR_LOW_358_D0000
    #spoken premier set bipolar low
    #response "premier set bipolar low\r"
#end_phrase
#phrase !PREMIER_REPORT_BIPOLAR_705_D0000
    #spoken premier report bipolar
    #response "premier report bipolar\r"
#end_phrase
#phrase !PREMIER_GO_TO_FRAG
    #spoken premier go to fragmentation
    #response "premier goto fragmentation\r"
#end_phrase
#phrase !PREMIER_END_VITRECTOMY_334_724_436_D0000
    #spoken premier tEND scissors
    #response "premier "tEND" scissors\r"
#end_phrase
#phrase !PREMIER_GO_TO_VITRECTOMY_478_391_D0000
    #spoken premier go to vitrectomy
    #response "premier goto vitrectomy\r"
#end_phrase
```

```
#phrase !SAMPLE_NOISE_DIALOG_BOX_D0007,\NO_MOD_ALL
    #spoken sample noise
    #response ""
#end_phrase
```

```
#main structure
#end structure
```

```
#end grammar
```

```
;; -----
;;      Fragmentation Grammar
;; -----
```

```
#grammar "Frag"

#context
"CONTEXT=*,#32770,Fragmentation"
#end_context
```

```
#phrase !STOP_LISTENING_PROGRAM_MANAGER_041,\NO_MOD_RESPONSE,1
    #spoken stop listening
```

- 22V -

```
#response "$I$"
#end_phrase
#phrase !PREMIER_SET_BIPOLAR_HIGH_041,\INACTIVE,1
    #spoken premier set bipolar high
    #response "premier set bipolar high\r"
#end_phrase
#phrase !PREMIER_SET_POWER_LOW_145
    #spoken premier set power low
    #response "premier set power low\r"
#end_phrase
#phrase !PREMIER_SET_POWER_HIGH_281
    #spoken premier set power high
    #response "premier set power high\r"
#end_phrase
#phrase !PREMIER_SET_PULSE_RATE_HIGH_961
    #spoken premier pulse on
    #response "premier set pulse rate high\r"
#end_phrase
#phrase !PREMIER_SET_PULSE_RATE_LOW_961
    #spoken premier pulse off
    #response "premier set pulse rate low\r"
#end_phrase
#phrase !PREMIER_SET_ASPIRATION_LOW_334_D0001_491
    #spoken premier set aspiration low
    #response "premier set aspiration low\r"
#end_phrase
#phrase !PREMIER_SET_ASPIRATION_HIGH_334_D0001_995
    #spoken premier set aspiration high
    #response "premier set aspiration high\r"
#end_phrase
#phrase !PREMIER_REPORT_ASPIRATION_467_041_942
    #spoken premier report aspiration
    #response "premier report aspiration\r"
#end_phrase
#phrase !PREMIER_REPORT_PULSE_RATE_827
    #spoken premier report pulse rate
    #response "premier report pulse rate\r"
#end_phrase
#phrase !PREMIER_REPORT_POWER_436
    #spoken premier report power
    #response "premier report power\r"
#end_phrase
#phrase !PREMIER_SET_BIPOLAR_LOW_358_D0001,\INACTIVE,1
    #spoken premier set bipolar low
    #response "premier set bipolar low\r"
#end_phrase
#phrase !PREMIER_REPORT_BIPOLAR_705_D0001,\INACTIVE,1
    #spoken premier report bipolar
    #response "premier report bipolar\r"
#end_phrase
#phrase !PREMIER_GO_TO_PHACO_D0001
    #spoken premier go to scissors
    #response "premier goto scissors\r"
#end_phrase
#phrase !PREMIER_END_VITRECTOMY_334_724_436_D0001
    #spoken premier END fragmentation
```

```
#response "premier \"END\" fragmentation\r"
#end_phrase
#phrase !PREMIER_GO_TO_VITRECTOMY_478_391_D0001
  #spoken premier go to vitrectomy
  #response "premier goto vitrectomy\r"
#end_phrase
```

```
#phrase !SAMPLE_NOISE_DIALOG_BOX_D0008, \NO_MOD_ALL
  #spoken sample noise
  #response ""
#end_phrase
```

```
#main structure
#end_structure

#end grammar
```

```
#include "global.inc" ; Required Listen include file
```

```
#end vocabulary
#end_application
```

- 22X -
APPENDIX B

```
// premier.cpp : Defines the class behaviors for the application.
//

#include "stdafx.h"
#include "premier.h"
#include "mydialog.h"
#include "mainfrm.h"
#include "premidoc.h"
#include "premivw.h"
#include <skelton.hpp>

#ifndef _DEBUG
#define THIS_FILE
static char BASED_CODE THIS_FILE[] = __FILE__;
#endif

extern "C"
{
    #include "c:\msvc\bin\pushbtn.c"
}

///////////
///
// CPremierApp

BEGIN_MESSAGE_MAP(CPremierApp, CWinApp)
    //{{AFX_MSG_MAP(CPremierApp)
    ON_COMMAND(ID_APP_ABOUT, OnAppAbout)
    ON_COMMAND(ID_RUN_ANT, OnRunAnt)
    ON_COMMAND(ID_RUN_POST, OnRunPost)
    ON_COMMAND(ID_UTIL_BUTTON_PRESS, OnUtilButtonPress)
    //}}AFX_MSG_MAP
    // Standard file based document commands
    ON_COMMAND(ID_FILE_NEW, CWinApp::OnFileNew)
    ON_COMMAND(ID_FILE_OPEN, CWinApp::OnFileOpen)

END_MESSAGE_MAP()

///////////
///
// CPremierApp construction

CPremierApp::CPremierApp()
{
    // TODO: add construction code here,
    // Place all significant initialization in InitInstance
}

///////////
///
// The one and only CPremierApp object
```

```
CPremierApp NEAR theApp;

///////////
/// 
// CPremierApp initialization

BOOL CPremierApp::InitInstance()
{
    // Standard initialization
    // If you are not using these features and wish to reduce the size
    // of your final executable, you should remove from the following
    // the specific initialization routines you do not need.

    SetDialogBkColor();           // set dialog background color to gray
    LoadStdProfileSettings();    // Load standard INI file options
(including MRU)

    // Register the application's document templates. Document
templates
    // serve as the connection between documents, frame windows and
views.

    AddDocTemplate(new CSingleDocTemplate(IDR_MENU1,
        RUNTIME_CLASS(CPremierDoc),
        RUNTIME_CLASS(CMainFrame),           // main SDI frame window
        RUNTIME_CLASS(CPremierView)));

    // create a new (empty) document
    OnFileNew();

    if (m_lpCmdLine[0] != '\0')
    {
        // TODO: add command line processing here
    }

    return TRUE;
}

///////////
// 
// CAboutDlg dialog used for App About

class CAboutDlg : public CDialog
{
public:
    CAboutDlg();

    // Dialog Data
    //{{AFX_DATA(CAboutDlg)
    enum { IDD = IDD_ABOUTBOX };
    //}}AFX_DATA

    // Implementation
protected:
```

- 22Z -

```
virtual void DoDataExchange(CDataExchange* pDX); // DDX/DDV support
//{{AFX_MSG(CAboutDlg)
//  // No message handlers
//}}AFX_MSG
DECLARE_MESSAGE_MAP()
};

CAboutDlg::CAboutDlg() : CDialog(CAboutDlg::IDD)
{
//{{AFX_DATA_INIT(CAboutDlg)
//}}AFX_DATA_INIT
}

void CAboutDlg::DoDataExchange(CDataExchange* pDX)
{
CDialog::DoDataExchange(pDX);
//{{AFX_DATA_MAP(CAboutDlg)
//}}AFX_DATA_MAP
}

BEGIN_MESSAGE_MAP(CAboutDlg, CDialog)
//{{AFX_MSG_MAP(CAboutDlg)
//  // No message handlers
//}}AFX_MSG_MAP
END_MESSAGE_MAP()

// App command to run the dialog
void CPremierApp::OnAppAbout()
{
    CAboutDlg aboutDlg;
    aboutDlg.DoModal();
}

///////////////
///
// CPremierApp commands

//Procedure to play a sound
void FAR PASCAL CppSndPlaySound (LPSTR sndName, UINT sndType) {

    BOOL (FAR PASCAL *lpPlaySound) (LPCSTR sndIs, UINT flags);

    lpPlaySound =
(lpSndCall)GetProcAddress(GetModuleHandle("MMSYSTEM"), "SNDPLAYSOUBD");

    if (lpPlaySound) (*lpPlaySound) (sndName, sndType);
}

void push_button(int button, DWORD ptime) {
    DWORD start_time;
    press(button);
    start_time=GetCurrentTime();
    while ((GetCurrentTime()-start_time)< ptime) {}
    release();
}
```

- 22AA -

```
void pause(DWORD ptime) {
    DWORD start_time;
    start_time=GetCurrentTime();
    while ((GetCurrentTime()-start_time)< ptime) {}
}

void initialize_anterior() {
    push_button(3,1000);           // Goto Phaco Mode
    pause(250);
    push_button(3,1000);
    pause(250);
    push_button(19,2050);         // Set Max Phaco to 50
    pause(250);
    push_button(4,1000);          // Goto Vitr Mode
    pause(250);
    push_button(23,4300);         // Set Max Asp to 150
    pause(250);
    push_button(4,1000);          // Leave Vitr Mode
}

// Procedure to bring up dialog box on command "Run:Begin"
void CPremierApp::OnRunAnt()
{
    CMyDialog2 MsgBox;
    CIntroDialog IntroBox;
    CVitrDialog VitBox;
    CAntMainDialog NoModeBox;
    CIrrAspDialog IrrAspBox;
    CPhacoDialog PhacoBox;
    CMydialog4 ButtonBox;
    CString Reply,Caption;
    DWORD start_time,difftime;
    CStringArray WordList;
    int nleft,nright,i,num,diff;
    int cutrate, aspiration;

    Caption = "Confirm";
    CppSndPlaySound("c:\\msvc\\bin\\premier\\befant.wav",0x0001);
    MessageBox(NULL,"Ready to begin?",Caption,MB_OK);
    CppSndPlaySound("c:\\msvc\\bin\\premier\\befinit.Wav",0x0001);
    initialize_anterior();
    while (NoModeBox.entry!="premier end program") {
        if (NoModeBox.entry=="premier goto vitrectomy") {
            VitBox.entry="";
            push_button(4,1000);
            CppSndPlaySound("c:\\msvc\\bin\\premier\\invimode.wav",0x0001);
        }
        else {
            if (NoModeBox.entry=="premier goto phaco") {
                PhacoBox.entry="";
                push_button(3,1000);
                pause(250);
                push_button(3,1000);
            }
        }
    }
}
```

- 22BB -

```
        CppSndPlaySound("c:\\msvc\\bin\\premier\\inphmode.wav",0x0001,);
    }
    else {
        if (NoModeBox.entry=="premier goto IA") {
            IrrAspBox.entry="";
            push_button(2,1000);

            CppSndPlaySound(ec:\\msvc\\bin\\premier\\iniamode.wav",0x0001);
        }
        else {
            NoModeBox.entry="";
            CppSndPlaySound("-
c:\\msvc\\bin\\premier\\selmode.wav",0x0001);
            NoModeBox.DoModal();
        }
    }
while (VitBox.entry!="premier end vitrectomy") {
    VitBox.entry="";
    VitBox.DoModal();
    if (VitBox.entry!="premier end vitrectomy") {
        if (Vitbox.entry=="premier set cutrate high") {
            CppSndPlaySound ("c
\\msvc\\bin\\premier\\set_cuth.wav",0x0001);
            if (MessageBox(NULL,VitBox.entry,Caption,MB
OKCANCEL)==IDOK) {
                if (VitBox.cutrate==300) {

                    CppSndPlaySound("C:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                    push_button(21,2200);
                    VitBox.cutrate=600;
                }
                CppSndPlaySound("c:\\msvc\\bin\\premier\\rcuth.wav",0x0001);
            }
        }
        if (VitBox.entry=="premier set cutrate low") {
            CppSndPlaySound('c:\\msvc\\bin\\premier\\set_cutl.wav",0x0001);
            if (MessageBox(NULL,VitBox.entry,Caption,MB_OKCANCEL)==IDOK) {
                if (VitBox.cutrate==600) {

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                    push_button(22,2200);
                    VitBox.cutrate=300;
                }
                CppSndPlaySound("c:\\msvc\\bin\\premier\\rcutl.wav",0x0001);
            }
        }
        if (VitBox.entry=="premier set aspiration high") {
            CppSndPlaySound("c:\\msvc\\bin\\premier\\set_asph.wav",0x0001);
            if (MessageBox(NULL,VitBox.entry,Caption,MB_OKCANCEL)==IDOK) {
                if (VitBox.aspiration==150) {

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                    push_button{23,5200);
                    VitBox.aspiration=300;
                }
            }
        }
    }
}
```

- 22CC -

```
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rvaph.wav",0x0001);
    }
}
if (VitBox.entry=="premier set aspiration low") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\set_aspl.wav",0x0001);
    if (MessageBox(NULL,VitBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (VitBox.aspiration==300) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button(24,5200);
            VitBox.aspiration=150;
        }
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rvaspl.wav",0x0001);
    }
}
if (VitBox.entry=="premier report aspiration") {
    if (VitBox.aspiration==300)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\rvaph.wav",0x0001);
        else
    CppSndPlaySound("c:\\msvc\\bin\\premier\\rvaspl.wav",0x0001);
}
if (VitBox.entry=="premier report cut rate") {
    if (VitBox.cutrate==600)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\rcuth.wav",0x0001);
        else
    CppSndPlaySound("c:\\msvc\\bin\\premier\\rcutl.wav",0x0001);
}
if ((VitBox.entry=="premier goto phaco") || (VitBox.entry=="premier
goto IA")) {
    NoModeBox.entry=VitBox.entry;
    VitBox.entry="premier end vitrectomy";
}
}
else {
    push_button(4,1000);
    NoMode.Box.entry="";
}
}

if (VitBox.entry=="pb")
if (ButtonBox.DoModal()) {
    difftime=ButtonBox.time_msec;
    press(ButtonBox button);
    start_time=GetCurrentTime();
    while (GetCurrentTime()-start_time_difftime) {}
    release();
}
}
while (PhacoBox.entry!="premier end phaco") {
    PhacoBox entry="";
    PhacoBox DoModal();
    if (PhacoBox.entry!="premier end phaco") {
        if (PhacoBox.entry=="premier set maxphaco high") {
```

- 22DD -

```
CppSndPlaySound("c:\\msvc\\bin\\premier\\smaxphhi.wav",0x0001);
    if (MessageBox
(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.maxphaco==50) {

CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
    push_button (19,2200):
    PhacoBox.maxphaco=100;
}
else
CppSndPlaySound("c:\\msvc\\bin\\premier\\rmxphhi.wav",0x0001);
}
if (PhacoBox.entry=="premier set maxphaco low") {

CppSndPlaySound("c:\\msvc\\bin\\premier\\smaxphlo.wav",0x0001);
    if (MessageBox(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.maxphaco==100) {
            CppSndPlaySound("c:\\
\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button(20,2200);
            PhacoBox.maxphaco=50;
}
            CppSndPlaySound
("c:\\\\msvc\\\\bin\\\\premier\\\\rmxphlo.wav",0x0001);
}
if (PhacoBox.entry=="premier set minphaco high") {
    CppSndPlaySound("c:\\\\msvc\\\\bin\\\\premier\\\\sminphhi.wav",0x0001);
    if (MessageBox(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.minphaco==5) {

CppSndPlaySound("c:\\\\msvc\\\\bin\\\\premier\\\\plswait.wav",0X0001);
        push_button (17, 1450);
        PhacoBox.minphaco=30;
}
        CppSndPlaySound("c:\\\\msvc\\\\bin\\\\premier\\\\rmnphhi.wav",0x0001);
}
if (PhacoBox.entry=="premier set minphaco low") {
    CppSndPlaySound ("c:\\\\msvc\\\\bin\\\\premier\\\\sminphlo.wav",0x0001);
    if (MessageBox(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.minphaco==30) {

CppSndPlaySound("c:\\\\msvc\\\\bin\\\\premier\\\\plswait.wav",0x0001);
        push_button(18,1450);
        PhacoBox.minphaco=5;
}
        CppSndPlaySound("c:\\\\msvc\\\\bin\\\\premier\\\\rmnphlo.wav",0x0001);
}
if (PhacoBox.entry=="premier set aspiration low") {
    CppSndPlaySound ("c:\\\\msvc\\\\bin\\\\premier\\\\set_aspl.wav",0x0001);
    if (MessageBox(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.fixedasp==60) {
```

- 22EE -

```
CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
    push_button(24,1650);
    PhacoBox.fixedasp=30;
}
CppSndPlaySound("c:\\msvc\\bin\\premier\\rasplo.wav",0x0001);
}
if (PhacoBox.entry=="premier set aspiration high") {

CppSndPlaySound("c:\\msvc\\bin\\premier\\set_asph.wav",0x0001);
    if (MessageBox(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.fixedasp==30) }

CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
    push_button(23,1650);
    PhacoBox.fixedasp=60;
}
CppSndPlaySound("c:\\msvc\\bin\\premier\\rasphi.wav",0x0001);
}
if (PhacoBox.entry=="premier set pulserate low") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\spulselo.wav",0x0001);
    if (MessageBox(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.pulserate==0) {

CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
    push_button(21,1300);
    PhacoBox.pulserate=4;
}
else {
    if (PhacoBox.pulserate==8) {

CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
    push_button(22,1300);
    PhacoBox.pulserate=4;
}
}
CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
}
}
if (PhacoBox.entry=="premier set pulserate high") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\spulsehi.wav",0x0001);
    if (MessageBox(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.pulserate==0) {

CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
    push_button(21,1900);
    PhacoBox.pulserate=8;
}
else {
    if (PhacoBox.pulserate==4) {

CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
    push_button(21,1300);
    PhacoBox.pulserate=8;
```

- 22FF -

```

        }
    }
    CppSndPlaySound("c:\\msvc\\bin\\premier\\rpulshi.wav",0x0001);
}
}
if (PhacoBox.entry=="premier set pulserate off") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\spulseze.wav",0x0001);
    if (MessageBox(NULL,PhacoBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (PhacoBox.pulserate==8) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button(22,1900);
            PhacoBox.pulserate=0;
        }
        else {
            if (PhacoBox.pulserate==4) {

                CppSndPlaySound("c:\\msvc\\bin\\premier\\plswaitwav",0x0001);
                push_button(22,1300);
                PhacoBox.pulserate=0;
            }
        }
    }
    CppSndPlaySound("c:\\msvc\\bin\\premier\\rpulsze.wav",0x0001);
}
}
if (PhacoBox.entry=="premier report pulse rate") {
    if (PhacoBox.pulserate==8)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\rpulslo.wav",0x0001);
        else {
            if (PhacoBox.pulserate==4)

                CppSndPlaySound("c:\\msvc\\bin\\premier\\rpulslo.wav",0x0001);
                else
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rpulsze.wav",0x0001);

    }
}
if (PhacoBox.entry=="premier report aspiration") {
    if (PhacoBox.fixedasp==60)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\rasphi.wav",0x0001);
        else
    CppSndPlaySound("c:\\msvc\\bin\\premier\\rasplo.wav",0x0001);
}
if (PhacoBox.entry=="premier report max phaco") {
    if (PhacoBox.maxphaco==100)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\rmxphhi.wav",0x0001);
        else
    CppSndPlaySound("c:\\msvc\\bin\\premier\\rmxphlo.wav",0x0001);
}
if (PhacoBox.entry=="premier report min phaco") {
    if (PhacoBox.minphaco==30)
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rmnphhi.wav",0x0001);
        else CppSndPlaySound("c:\\msvc\\bin\\premier\\rmnphlo.wav",0x0001);
}

```

- 22GG -

```

        }
        if ((PhacoBox.entry=="premier goto vitrectomy") || (PhacoBox.
          NoModeBox.entry=PhacoBox.entry;
          PhacoBox.entry="premier end phaco";
        }
      }
      else {
        push_button(3,1000);
        NoModeBox.entry="";
      }
    }
  while (IrrAspBox.entry!="premier end IA") {
    IrrAspBox.entry="";
    IrrAspBox.DoModal();
    if (IrrAspBox.entry=="premier end IA") {
      push_button(2,1000);
      pause(250);
      push_button(2,1000);
      NoModeBox.entry="";
    }
    if ((IrrAspBox.entry=="premier goto
phaco") || (IrrAspBox.entry=="premier goto vitrectomy")){
      NoModeBox.entry=IrrAspBox.entry;
      IrrAspBox.entry="premier end IA";
    }
  }
  push_button(14,1000);
}

void initialize_posterior() {
  /*push_button(1,1000);                                //Goto Vitr Mode
  pause(250);
  push_button(23,4300);                                // Set Max Asp to 150
  pause(250);
  push_button(6,1000);                                // Turn on IOP
  pause(250);
  push_button(15,3700);                                // Set IOP to 40
  pause(250);
  push_button(6,1000);                                // Turn off IOP
  pause(250); */
  push_button(2,1000);                                // Goto Frag Mode
  pause(250);
  /*push_button(19,1200);                                // Set Frag Power to 8
  pause(250); */
  push_button(24,2200);                                // Set Max Asp to 150
  pause(250);
  push_button(3,1000);                                // Goto Scissors : Variable Rate
  pause(250);
  push_button(3,1000);
  pause(280);
  push_button(21,1900);                                // Set cut rate to 120
  pause(250);
  push_button(3,1000);                                // Leave Scissors
  pause(250);
  push_button(3,1000);
}

```

- 22HH -

```
    pause(250);
    /*
    push_button(4,1000);                      // Turn on Bipolar -
    pause(250);
    push_button(19,2850);                     // Set Bipolar to 16
    pause(250);    */
}

void CPremierApp::OnRunPost()
{
    CFragmentDialog FragBox;
    CPostVitrDialog VitBox;
    CScissorDialog SBox;
    CPostMainDialog NoModeBox;
    CMydialog4 ButtonBox;
    CString Caption;
    DWORD start_time,difftime;
    int bip;

    Caption = "Confirm";
    CppSndPlaySound("c:\\msvc\\bin\\premier\\befpost.wav",0x0001);
    MessageBox(NULL,"Ready to begin?",Caption,MB_OK);
    CppSndPlaySound("c:\\msvc\\bin\\premier\\befinit.wav",0x0001);
    initialize_posterior();
    bip = 16;
    while (NoModeBox.entry!="premier end program") {
        if (NoModeBox.entry=="premier goto vitrectomy") {
            VitBox.entry="";
            push_button(1,1000);                      // Vitr button
            pause(250);
            push_button(4,1000);                      // Turn on Bipolar

            CppSndPlaySound("c:\\msvc\\bin\\premier\\invimode.wav",0x0001);
        }
        else{
            if (NoModeBox.entry=="premier goto fragmentation") {
                FragBox.entry="";
                push_button(2,1000);

                CppSndPlaySound("c:\\msvc\\bin\\premier\\infrmode.wav",0x0001);
            }
            else {
                if (NoModeBox.entry=="premier goto scissors") {
                    SBox.entry="";
                    push_button(1,1000);
                    pause(250);
                    push_button(3,1000);
                    pause(250);
                    push_button(4,1000);                      // Turn on Bipolar

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\inscmode.wav",0x0001);
                }
                else{
                    NoModeBox.entry="";
                }
            }
        }
    }
}
```

- 22II -

```
    CppSndPlaySound("c:\\msvc\\bin\\premier\\selmode.wav",0x0001);
        NoModeBox.DoModal();
    }
}
while (VitBox.entry!="premier end vitrectomy") {
    VitBox.entry="";
    VitBox.bipolar=bip;
    VitBox.DoModal();
    if (VitBox entry!="premier end vitrectomy") {
        if (VitBox.entry=="premier set cutrate high") {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\set_cuth.wav",0x0001);
            if (MessageBox(NULL,VitBox.entry,Caption,MB_OKCANCEL)==IDOK) {
                if (VitBox.cutrate==300) {

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                    push_button(21,2200);
                    VitBox.cutrate=600;

                }
            }
            CppSndPlaySound("c:\\msvc\\bin\\premier\\rcuth.wav",0x0001);
        }
    }
    if (VitBox.entry=="premier set cutrate low") {
        CppSndPlaySound("c:\\msvc\\bin\\premier\\set_cutl.wav",0x0001);
        if (MessageBox(NULL,VitBox.entry,Caption,MB_OKCANCEL)==IDOK) {
            if (VitBox.cutrate==600) {

                CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                push_button(22,2200);
                VitBox.cutrate=300;
            }
            CppSndPlaySound("c:\\msvc\\bin\\premier\\rcutl.wav",0x0001);
        }
    }
    if (VitBox.entry=="premier set aspiration high") {
        CppSndPlaySound("c:\\msvc\\bin\\premier\\set_asph.wav",0x0001);
        if (MessageBox(NULL,VitBox.entry,Caption,MB_OKCANCEL)==IDOK) {
            if (VitBox.aspiration==150) {

                CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                push_button(23,5200);
                VitBox.aspiration=300;
            }
        }
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rvaph.wav",0x0001);
    }
}
if (VitBox.entry=="premier set aspiration low") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\set_aspl.wav",0x0001);
    if (MessageBox(NULL,VitBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (VitBox.aspiration==300) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);

```

- 22JJ -

```
    push_button(24, 5200);
    VitBox.aspiration=150;
}

CppSndPlaySound("c:\\msvc\\bin\\premier\\rvaspl.wav", 0x0001);
}
}
if (VitBox.entry=="premier set bipolar low") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\setbiplo.wav", 0x0001);
    if (MessageBox(NULL, VitBox.entry, Caption, MB_OKCANCEL) == IDOK) {
        if (bip==22) {

    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav", 0x0001);
        push_button(20, 1150);
        bip=16;
    }

    CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiplo.wav", 0x0001);
}
}
if (VitBox.entry=="premier set bipolar high") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\setbiphi.wav", 0x0001);
    if (MessageBox(NULL, VitBox.entry, Caption, MB_OKCANCEL) == IDOK) {
        if (bip==16) {

    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav", 0x0001);
        push_button(19, 1150);
        bip=22;
    }

    CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiphi.wav", 0x0001);
}
}
if (VitBox.entry=="premier gas on") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\setgason.wav", 0x0001);
    if (MessageBox(NULL, VitBox.entry, Caption, MB_OKCANCEL) == IDOK) {
        if (VitBox.iopstatus=="OFF") {
            push_button(6, 1000);
            VitBox.iopstatus="ON";
        }
    }

    CppSndPlaySound("c:\\msvc\\bin\\premier\\repgason.wav", 0x0001);
}
}
if (VitBox.entry=="premier gas off") {

    CppSndPlaySound("c:\\msvc\\bin\\premier\\setgasof.wav", 0x0001);
    if (MessageBox(NULL, VitBox.entry, Caption, MB_OKCANCEL) == IDOK) {
        if (VitBox.iopstatus=="ON") {
            push_button(6, 1000);
            VitBox.iopstatus="OFF";
        }
    }

    CppSndPlaySound("c:\\msvc\\bin\\premier\\repgasof.wav", 0x0001);
}
}
if (VitBox.entry=="premier report aspiration") {
```

- 22KK -

```
        if (VitBox.aspiration==300)

            CppSndPlaySound("c:\\msvc\\bin\\premier\\rvaph.wav",0x0001);
            else
                CppSndPlaySound("c:\\msvc\\bin\\premier\\rvapl.wav",0x0001);
            }
            if (VitBox.entry=="premier report gas") {
                if (VitBox.iopstatus=="ON")

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\repgason.wav",0x0001);
                    else
                        CppSndPlaySound("c:\\msvc\\bin\\premier\\repgasoff.wav",0x0001);
                    }
                    if (VitBox.entry=="premier report bipolar") {
                        if (bip==22)

                            CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiphi.wav",0x0001);
                            else
                                CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiplo.wav",0x0001);
                            }
                            if (VitBox.entry=="premier report cut rate") {
                                if (VitBox.cutrate==600)

                                    CppSndPlaySound("c:\\msvc\\bin\\premier\\rcuth.wav",0x0001);
                                    else
                                        CppSndPlaySound("c:\\msvc\\bin\\premier\\rcutl.wav",0x0001);
                                    }
                                    if ((VitBox.entry=="premier goto
fragmentation")||(VitBox.entry=="premier goto scissors")) {
                                        NoModeBox.entry=VitBox.entry;
                                        VitBox.entry="premier end vitrectomy";
                                        if (VitBox.iopstatus=="ON") {
                                            VitBox.iopstatus="OFF";
                                            push_button(6,1000);
                                        }
                                        pause(250);
                                        push_button(4,1000); // Turn off Bipolar
                                    }
                                    if (VitBox.entry=="pb")
                                        if (ButtonBox.DoModal()) {
                                            difftime=ButtonBox.time_msec;
                                            press(ButtonBox.button);
                                            start_time=GetCurrentTime();
                                            while (GetCurrentTime()-start_time<difftime) {}
                                            release();
                                        }
                                    }
                                    else {
                                        if (VitBox.iopstatus=="ON") {
                                            VitBox.iopstatus="OFF";
                                            push_button(6,1000);
                                        }
                                        push_button(1,1000);
                                        pause(250);
                                        push_button(4,1000); // Turn off Bipolar
                                        NoModeBox.entry="";
                                    }
```

- 22LL -

```
        )
    }
    while (FragBox.entry!="premier end fragmentation")  {
        FragBox.entry="";
        FragBox.bipolar=bip;
        FragBox.DoModal();
        if (FlagBox.entry=="premier set bipolar low:")  {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\setbipol.wav",0x0001);
            if (MessageBox (NULL,FragBox.entry,Caption,MB_OKCANCEL)==IDOK)  {
                if (bip==22)  {

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                    push_button (18,1450);
                    bip=16;
                }

                CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiplo.wav",0x0001);
            }
        }
        if (FragBox.entry=="premier set bipolar high")  {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\setbiphi.wav",0x0001);
            if (MessageBox (NULL,FragBox.entry,Caption,MB_OKCANCEL)==IDOK)  {
                if (bip==16)  {

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                    push_button(17,1450);
                    bip=22;
                }

                CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiphi.wav",0x0001);
            }
        }
        if (FragBox.entry=="premier set power high")  {
            CppSndPlaySound("c:\\msvc\\bin\\premier\\setpowhi.wav",0x0001);
            if (MessageBox (NULL,FragBox.entry,Caption,MB_OKCANCEL)==IDOK)  {
                if (FragBox.fragpower==5)  {

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                    push_button(19,1150);
                    FragBox.fragpower=20;
                }

                CppSndPlaySound("c:\\msvc\\bin\\premier\\reppowhi.wav",0x0001);
            }
        }
        if (FragBox.entry=="premier see power low")  {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\setpowlo.wav",0x0001);
            if (MessageBox (NULL,FragBox.entry,Caption,MB_OKCANCEL)==IDOK)  {
                if (FragBox.fragpower==20)  {

                    CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
                    push_button(20,1150);
                    FragBox.fragpower= 5;
                }
            }
        }
    }
}
```

- 22MM -

```
}

CppSndPlaySound("c:\\msvc\\bin\\premier\\reppowlo.wav",0x0001);
}
}

if (FragBox.entry=="premier set aspiration high") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\set_asph.wav",0x0001);
    if (MessageBox(NULL,FragBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (FragBox.aspiration==150) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button(23,5200);
            FragBox.aspiration=300;
        }
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rfasphi.wav",0x0001);
    }
}
if (FragBox.entry=="premier set aspiration low") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\set_aspl.wav",0x0001);
    if (MessageBox(NULL,FragBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (FragBox.aspiration==300) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button (24,5200);
            FragBox.aspiration=150;
        }
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rtaspl0.wav",0x0001);
    }
}
if (FragBox.entry=="premier set pulse rate high") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\spulseon.wav",0X0001);
    if (MessageBox(NULL,FragBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (FragBox.pulserate==0) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button(21,1500);
            FragBox.pulserate=5;
        }
    }
}
if (FragBox.entry=="premier set pulse rate low") {
    CppSndPlaySound("c:\\msvc\\bin\\premier\\spulseof.wav",0x0001);
    if (MessageBox(NULL,FragBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (FragBox.pulserate==5) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button(22,1500);
            FragBox.pulserate=0;
        }
    }
}
if (FragBox.entry=="premier report aspiration") {
```

- 22NN -

```
        if (FragBox.aspiration==300)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\rfasphi.wav",0x0001);
        else
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rfasplo.wav",0x0001);
    }
    if (FragBox.entry=="premier report pulse rate") {
        if (FragBox.pulserate==5)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\repplson.wav",0x0001);
        else
        CppSndPlaySound("c:\\msvc\\bin\\premier\\repplsof.wav",0x0001);
    }
    if (FragBox.entry=="premier report power") {
        if (FragBox.fragpower==20)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\reppowhi.wav",0x0001);
        else
        CppSndPlaySound("c:\\msvc\\bin\\premier\\reppowlo.wav",0x0001);
    }
    if (FragBox.entry=="premier report bipolar") {
        if (bip==22)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiphi.wav",0x0001);
        else
        CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiplo.wav",0x0001);
    }
    if (FragBox.entry=="premier end fragmentation") {
        push_button(2,1000);
        NoModeBox.entry="";
    }
    if ((FragBox.entry=="premier goto
vitrectomy")||(FragBox.entry=="premier goto scissors")) {
        NoModeBox.entry=FragBox.entry;
        FragBox.entry="premier end fragmentation";
    }
}
while (SBox.entry!="premier end scissors") {
    SBox.entry="";
    SBox.bipolar=bip;
    SBox.DoModal();
    if (SBox.entry=="premier set cutrate low") {
        CppSndPlaySound(c:\\msvc\\bin\\premier\\set_cul1.wav",0x0001);
        if (MessageBox(NULL,SBox.entry,Caption,MB_OKCANCEL)==IDOK) {
            if (SBox.cutrate==200) {

        CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
        push_button(22,1900);
        SBox.cutrate=120;
    }
}
    CppSndPlaySound("c:\\msvc\\bin\\premier\\rscut1.wav",0x0001);
}
}
if (SBox.entry=="premier set cutrate high") {
```

- 2200 -

```
CppSndPlaySound("c:\\msvc\\bin\\premier\\set_cuth.wav",0x0001);
if (MessageBox(NULL,SBox.entry,Caption,MB_OKCANCEL)==IDOK) {
    if (SBox.cutrate==120) {

        CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
        push_button(21,1900);
        SBox.cutrate=200;
    }

    CppSndPlaySound("c:\\msvc\\bin\\premier\\rscuth.wav",0x0001);
}

if (SBox.entry=="premier set bipolar low") {

    CppSndPlaySound("c:\\msvc\\bin\\premier\\setbiplo.wav",0x0001);
    if (MessageBox(NULL,SBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (bip==22) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button(20,1150);
            bip=16;
        }

        CppSndPlaySound("c:\\msvc\\bin\\premier\\rephiplo.wav",0x0001);
    }
}

if (SBox.entry=="premier set bipolar high") {

    CppSndPlaySound("c:\\msvc\\bin\\premier\\setbiphi.wav",0x0001);
    if (MessageBox(NULL,SBox.entry,Caption,MB_OKCANCEL)==IDOK) {
        if (bip==16) {

            CppSndPlaySound("c:\\msvc\\bin\\premier\\plswait.wav",0x0001);
            push_button(19,1150);
            bip=22;
        }

        CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiphi.wav",0x0001);
    }
}

if (SBox.entry=="premier report bipolar") {
    if (bip==22)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiphi.wav",0x0001);
        else
        CppSndPlaySound("c:\\msvc\\bin\\premier\\repbiplo.wav",0x0001);
    }
}

if (SBox.entry=="premier report cut rate") {
    if (SBox.cutrate==200)

        CppSndPlaySound("c:\\msvc\\bin\\premier\\rscuth.wav",0x0001);
        else
        CppSndPlaySound("c:\\msvc\\bin\\premier\\rscutl.wav",0x0001);
}
```

- 22PP -

```
if (SBox.entry=="premier end scissors") {
    push_button(3,1000);
    pause(250);
    push_button(3,1000);
    pause(250);
    push_button(4,1000);           // Turn off Bipolar
    NoModeBox.entry="";
}
if ((SBox.entry=="premier goto vitrectomy") || (SBox.entry=="premier
goto fragmentation")) {
    NoModeBox.entry=SBox.entry;
    SBox.entry="premier end scissors";
    push_button(4,1000);           // Turn off Bipolar
}
}
push_button(14,1000);
}

void CPremierApp::OnUtilButtonPress()
{
    CButtonDialog ButtonBox;
    DWORD start_time, difftime;

    while (ButtonBox.DoModal() == IDOK)
    {
        difftime=ButtonBox.ptime;
        press(ButtonBox.button);
        start_time=GetCurrentTime();
        while (GetCurrentTime()-start_time<difftime) {}
        release();
    }
}
```

What Is Claimed Is

1. A voice controlled medical care system comprising:
a medical care device to be controlled in accordance
with commands spoken by an operator, said spoken commands
being selected from the group consisting of one of a number
of different command words, a command phrase comprising a
plurality of said command words, and a mixed phrase
comprising at least one of said command words and at least
one non-command word;

10 a microphone for transducing said spoken commands and
generating corresponding audio output signals; and

15 a processor comprising a first port connected to said
microphone for receiving said audio output signals, said
processor being programmable to substantially continuously
monitor said first port for said audio output signals, to
process said audio output signals to identify said command
words therein, and to generate corresponding control
signals for transmission to said medical care device.

20 2. A voice controlled medical care system as claimed in
claim 1, wherein said processor comprises at least one port
selected from the group consisting of a serial port and a
parallel port, and said medical care device is connected to
said processor via said port to receive said control
signals.

25 3. A voice controlled medical care system as claimed in
claim 1, wherein said processor is operable to generate
said control signals in a signal type selected from the
group consisting of an electrical signal, an infrared
signal, an ultrasonic signal, a radio frequency signal, and
30 an electromagnetic signal.

4. A voice controlled medical care system as claimed in claim 1, wherein said medical care device comprises at least one controllable device selected from the group consisting of a variable input device and a variable output device, and further comprising an interface circuit connected to said processor and said medical care device for operating said controllable device in accordance with said control signals.

5

5. A voice controlled medical care system as claimed in claim 4, wherein at least one of said processor and said interface circuit is operable to generate said control signals in a signal type selected from the group consisting of an electrical signal, an infrared signal, an ultrasonic signal, a radio frequency signal, and an electromagnetic signal.

10

6. A voice controlled medical care system as claimed in claim 1, wherein said spoken commands each comprise identification of said medical care device followed by a function of said medical care device that is being requested by said operator.

15

7. A voice controlled medical care system as claimed in claim 1, wherein said medical care device is an active surgical instrument, said processor being programmable to generate said control signals to control said surgical instrument during a surgical procedure.

20

8. A voice controlled medical care system as claimed in claim 1, wherein said medical care device is selected from the group consisting of a laser, an environmental control system, a surgical tool, an imaging device, a microscope,

25

patient prosthetic device, a patient mobilization device, and a patient monitoring device.

9. A voice controlled medical care system comprising:
5 a medical care device to be controlled in accordance with commands spoken by an operator, said spoken commands comprising at least one of a number of different command words, said medical care device having a plurality of controllable devices selected from the group consisting of a variable input device and a variable output device and being configured to operate in a plurality of functional modes by controlling selected ones of said controllable devices;

10 a microphone for transducing said spoken commands and generating corresponding audio output signals; and
15 a processor connected to said microphone for receiving said audio output signals, said processor being programmable to process said audio output signals to identify said command words therein, and to generate corresponding control signals for transmission to said medical care device, said control signals comprising data to configure said medical care device to perform an operation selected from the group consisting of changing from one to another one of said plurality of modes, and changing the setting of at least one of said plurality of controllable devices, as requested by said operator in said spoken commands.

20
25

10. A voice controlled medical care system as claimed in claim 9, wherein said processor is programmed to change settings of selected ones of said plurality of controllable devices and to restrict said operator from changing settings on other ones of said plurality of controllable
30

devices, depending on which of a particular one of said plurality of modes has been selected.

5 11. A voice controlled medical care system as claimed in claim 10, further comprising at least one output device selected from the group consisting of a display device and a speaker, said processor being programmable to operate said at least one output device to indicate when said operator is restricted from changing settings on different ones of said plurality of controllable devices.

10 12. A voice controlled medical care system as claimed in claim 9, wherein said processor is programmable to increase and decrease the settings of said plurality of controllable devices in increments.

15 13. A voice controlled medical care system as claimed in claim 12, wherein a characteristic of said control signals selected from the group consisting of duration, magnitude and number of said control signals corresponds to the amount the settings of said plurality of controllable devices are incremented and decremented.

20 14. A voice controlled medical care system as claimed in claim 12, wherein at least one of said plurality of controllable devices is nonlinear, said processor having stored data relating a characteristic of said control signals selected from the group consisting of duration, magnitude and number of said control signals to different settings of said nonlinear controllable device.

25 15. A voice controlled medical care system as claimed in claim 9, wherein said processor is programmable to

continuously increase and decrease the settings of said plurality of controllable devices.

5

16. A voice controlled medical care system as claimed in claim 15, wherein a characteristic of said control signals selected from the group consisting of duration, magnitude and number of said control signals corresponds to the amount the settings of said plurality of controllable devices are incremented and decremented.

10

17. A voice controlled medical care system as claimed in claim 15, wherein at least one of said plurality of controllable devices is nonlinear, said processor having stored data relating a characteristic of said control signals selected from the group consisting of duration, magnitude, and number of said control signals to different settings of said nonlinear controllable device.

15

18. A voice controlled medical care system as claimed in claim 9, wherein said processor is programmable to change the settings of said plurality of controllable devices from a current value to a value specified in said command words.

20

19. A voice controlled medical care system comprising:
a medical care device to be controlled in accordance with commands spoken by an operator, said spoken commands comprising at least one of a number of different command words, said medical care device having a plurality of controllable devices selected from the group consisting of a variable input device and a variable output device;

25

a microphone for transducing said spoken commands and generating corresponding audio output signals;

30

a processor connected to said microphone for receiving said audio output signals, said processor being

programmable to process said audio output signals to identify said command words therein, and to generate corresponding control signals for transmission to said medical care device, said control signals comprising data to change the settings of said plurality of controllable devices as requested by said operator in said spoken commands; and

5 a speaker connected to said processor;
wherein said spoken commands comprise a status query 10 relating to a selected one of said plurality of controllable devices, said processor being programmable to identify said status query and to provide status data relating to said selected controllable device to said operator via said speaker.

15 20. A voice controlled medical care system as claimed in claim 19, wherein said processor generates messages comprising said status data using a method selected from the group consisting of playing pre-recorded messages, and synthesizing voice messages using synthesized speech 20 program code.

21. A voice controlled medical care system comprising:
25 a medical care device to be controlled in accordance with commands spoken by an operator, said spoken commands comprising at least one of a number of different command words, said medical care device having a plurality of controllable devices selected from the group consisting of a variable input device and a variable output device;
a microphone for transducing said spoken commands and generating corresponding audio output signals;
30 a processor connected to said microphone for receiving said audio output signals, said processor being programmable to process said audio output signals to

5 identify said command words therein, and to generate corresponding control signals for transmission to said medical care device, said control signals comprising data to change the settings of said plurality of controllable devices as requested by said operator in said spoken commands; and

10 a speaker connected to said processor;
wherein said processor is programmable to provide a confirmation request to change the settings of said plurality of controllable devices as requested by said operator in said spoken commands to said operator via said speaker, and to suspend transmission of said corresponding control signals to said medical care device until said operator provides an acknowledgement command signal via said microphone and said processor identifies said acknowledgement command signal.

15

20 22. A voice controlled medical care system as claimed in claim 21, wherein said processor generates said confirmation request using a method selected from the group consisting of playing pre-recorded messages, and synthesizing voice messages using synthesized speech program code.

25 23. A voice controlled medical care system comprising:
at least one surgical tool to be controlled in accordance with commands spoken by an operator, said spoken commands comprising at least one of a number of different command words, said surgical tool having a plurality of controllable devices selected from the group consisting of a variable input device and a variable output device;
30 a microphone for transducing said spoken commands and generating corresponding audio output signals; and

5 a processor connected to said microphone for receiving said audio output signals, said processor being programmable in accordance with program code to process said audio output signals to identify said command words therein, and to generate corresponding control signals for transmission to said surgical tool, said control signals comprising data to change the setting of at least one of said plurality of controllable devices as requested by said operator in said spoken commands, said program code comprising a plurality of files corresponding, respectively, to a plurality of modes for operating said surgical tool, said plurality of files each comprising lists of selected ones of said command words which are valid for said surgical tool when operating in a corresponding one of said plurality of modes, said processor being programmable to use one of said plurality of files corresponding to the present one of said plurality of modes in which said surgical instrument is operating to identify said command words in said audio output signals.

10

15

20 24. A voice controlled medical care system as claimed in claim 23, wherein said processor is programmable to access said plurality of files in accordance with a logical sequence set forth in said program code, said logical sequence corresponding to a particular surgical procedure using said surgical tool.

25

30 25. A voice controlled medical care system as claimed in claim 23, wherein said plurality of files each comprise data allowing said operator to change settings of selected ones of said plurality of controllable devices and to restrict said operator from changing settings of other ones of said plurality of controllable devices, depending on

which of a particular one of said plurality of modes has been selected.

5

26. A voice controlled medical care system as claimed in claim 23, wherein said plurality of files each comprise data allowing said operator to go to selected ones of said plurality of modes, while restricting said operator from changing to certain other ones of said plurality of modes, depending on the particular one of said plurality of modes in which said surgical tool is operating.

10

15

27. A voice controlled medical care system as claimed in claim 23, further comprising a plurality of surgical tools, wherein said program code comprises at least one file for each of said plurality of surgical tools, said file comprising a list of selected ones of said command words which are valid for said surgical tool when said surgical tool is in use.

20

28. A voice controlled medical care system as claimed in claim 27, wherein said processor is programmable to use said file corresponding to an active one of said plurality of surgical tools to identify said command words in said audio output signals.

29. A method of controlling a medical care system, comprising the steps of:

25

receiving audio signals corresponding to commands spoken by an operator, said spoken commands being selected from the group consisting of one of a number of different command words, a command phrase comprising a plurality of said command words, and a mixed phrase comprising at least one of said command words and at least one non-command word;

30

identifying said command words in said audio signals;
and
controlling a medical care device in accordance with
said command words.

5 30. A method of controlling a medical care system as
claimed in claim 29, wherein said controlling step
comprises the step of generating a control signal for
transmission to said medical care device, said control
signal selected from the group consisting of an electrical
10 signal, an infrared signal, an ultrasonic signal, a radio
frequency signal, and an electromagnetic signal.

15 31. A method of controlling a medical care system as
claimed in claim 29, wherein said medical care device
comprises a plurality of controllable devices selected from
the group consisting of a variable input device and a
variable output device and is configured to operate in a
plurality of functional modes by controlling selected ones
20 of said plurality of controllable devices, and said
controlling step comprises the step of generating data to
configure said medical care device to perform an operation
selected from the group consisting of changing from one to
another one of said plurality of modes, and changing the
setting of at least one of said plurality of controllable
25 devices, as requested by said operator in said spoken
commands.

30 32. A method of controlling a medical care system as
claimed in claim 31, wherein said controlling step further
comprises the step of restricting said operator from
changing the setting of selected ones of said plurality of
controllable devices, depending on the particular one of

said plurality of modes in which said medical care device is operating.

5

33. A method of controlling a medical care system as claimed in claim 31, wherein said controlling step comprises the steps of increasing and decreasing the setting of a selected one of said plurality of controllable devices in increments in accordance with said spoken commands.

10

34. A method of controlling a medical care system as claimed in claim 31, wherein said controlling step comprises the steps of increasing and decreasing the setting of a selected one of said plurality of controllable devices continuously in accordance with said spoken commands.

15

35. A method of controlling a medical care system as claimed in claim 31, wherein at least one of said plurality of controllable devices is nonlinear, said controlling step comprising the steps of:

20

defining a relationship between different settings of said nonlinear controllable device and a characteristic of said control signals selected from the group consisting of duration, magnitude, and number of said control signals;

25 storing data relating to said relationship; and
accessing said data to operate said nonlinear controllable device in accordance with said spoken commands.

30

36. A method of controlling a medical care system as claimed in claim 31, wherein said controlling step further comprises the step of restricting said operator from changing to certain other ones of said plurality of modes.

depending on the particular one of said plurality of modes in which said medical care device is operating.

5 37. A method of controlling a medical care system as claimed in claim 29, wherein said spoken commands comprise a status query command, said controlling step comprising the step of generating a message reporting a condition of said medical care device in accordance with said status query command.

10 38. A method of controlling a medical care system as claimed in claim 37, wherein said generating step comprises the step of retrieving prerecorded messages from a memory device using a processor.

15 39. A method of controlling a medical care system as claimed in claim 37, wherein said generating step comprises the step of creating synthesized messages using a speech synthesizer.

40. A method of controlling a medical care system as claimed in claim 29, wherein said identifying step further comprises the step of generating a confirmation message.

20 41. A method of controlling a medical care system as claimed in claim 40, wherein said identifying step further comprises the steps of:

25 suspending said controlling step;
 receiving additional ones of said audio signals;
 determining if said spoken commands corresponding to said additional ones of said audio signals comprise an acknowledgment command;

commencing said controlling step if said acknowledgement is identified in said spoken words and is affirmative; and

5 canceling said controlling step if said acknowledgement is identified in said spoken words and is negative.

10

42. A method of controlling a medical care system as claimed in claim 41, wherein said identifying step further comprises the step of canceling said controlling step if said acknowledgement is not received.

15

43. A method of controlling a medical care system as claimed in claim 29, wherein said medical care device is a surgical tool, and said identifying step comprises the step of accessing a file corresponding to said surgical tool, said file comprising a list of valid commands for operating said surgical tool.

20

25

44. A method of controlling a medical care system as claimed in claim 29, wherein said medical care device is a surgical tool, and said identifying step comprises the step of accessing a plurality of files corresponding to said surgical tool, said files corresponding, respectively, to different modes of operating said surgical tool, each of said files comprising a list of valid commands for operating said surgical tool in said corresponding mode, said list of valid commands restricting access to selected ones of said plurality of files while an active one of said plurality of files is accessed in accordance with a logical sequence for performing a surgical procedure using said surgical tool.

5

45. A method of controlling a medical care system as claimed in claim 29, wherein said medical device comprises a plurality of surgical tools, and said identifying step comprises the step of accessing a file selected from a plurality of files corresponding, respectively, to a plurality of surgical tools, said selected file comprising a list of selected ones of said command words which are valid for a selected one of said plurality of surgical tools when said selected surgical tool is in use.

10

46. A voice controlled medical care system as claimed in claim 45, wherein said identifying step further comprises the step of using said file corresponding to said selected surgical tool to identify said command words in said audio output signals.

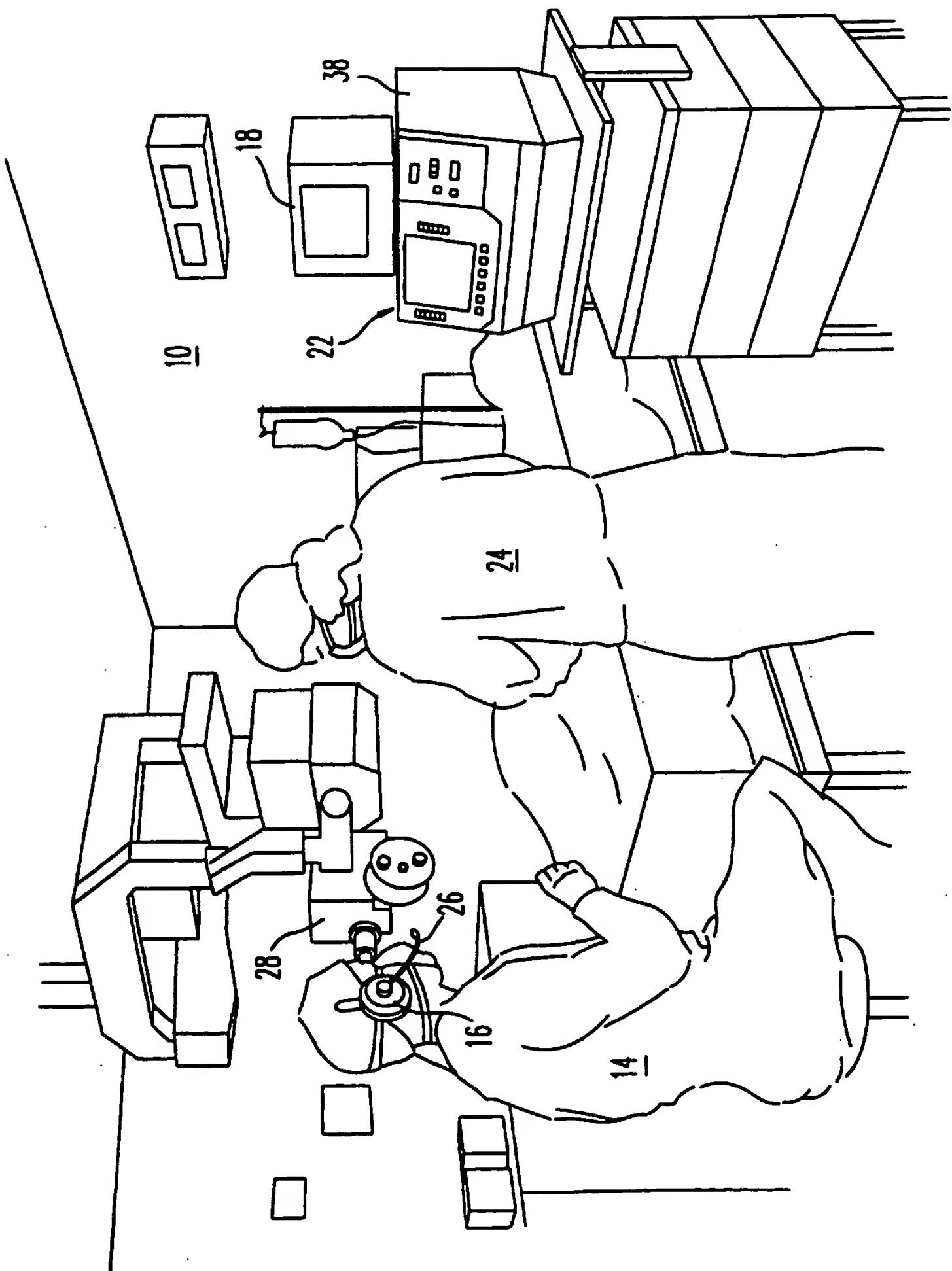


FIG. 1

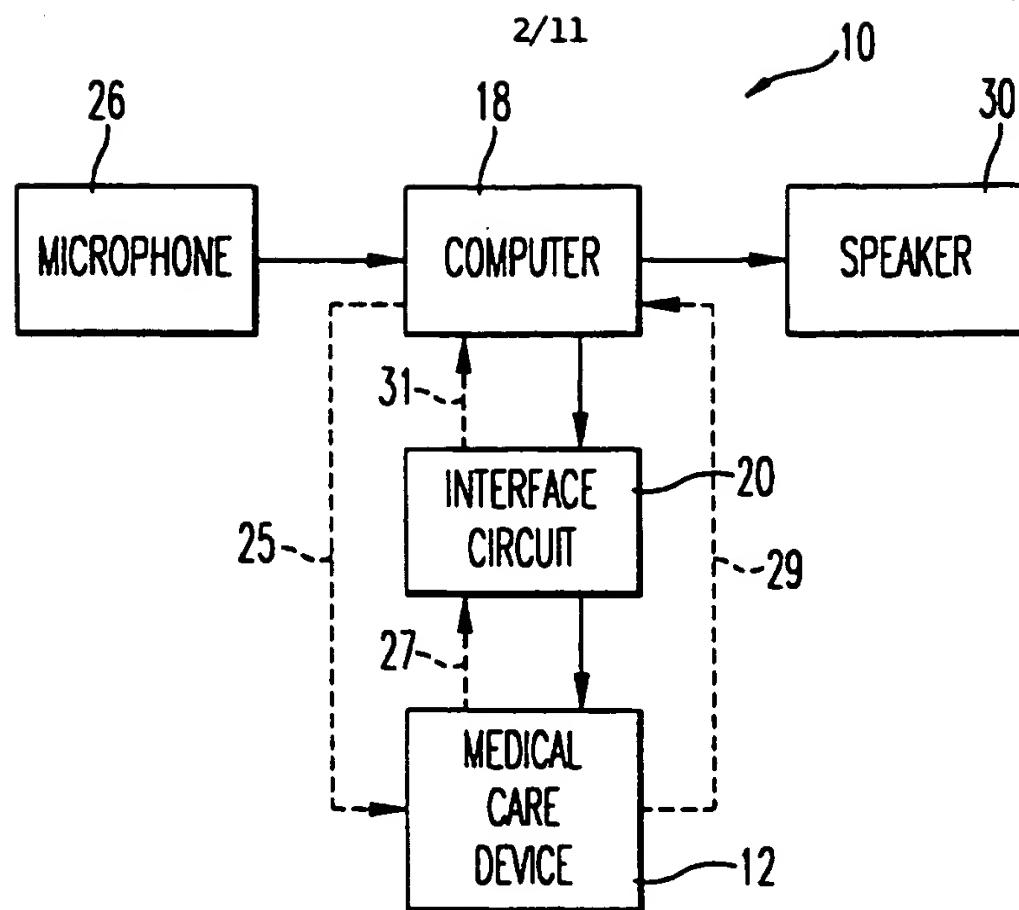
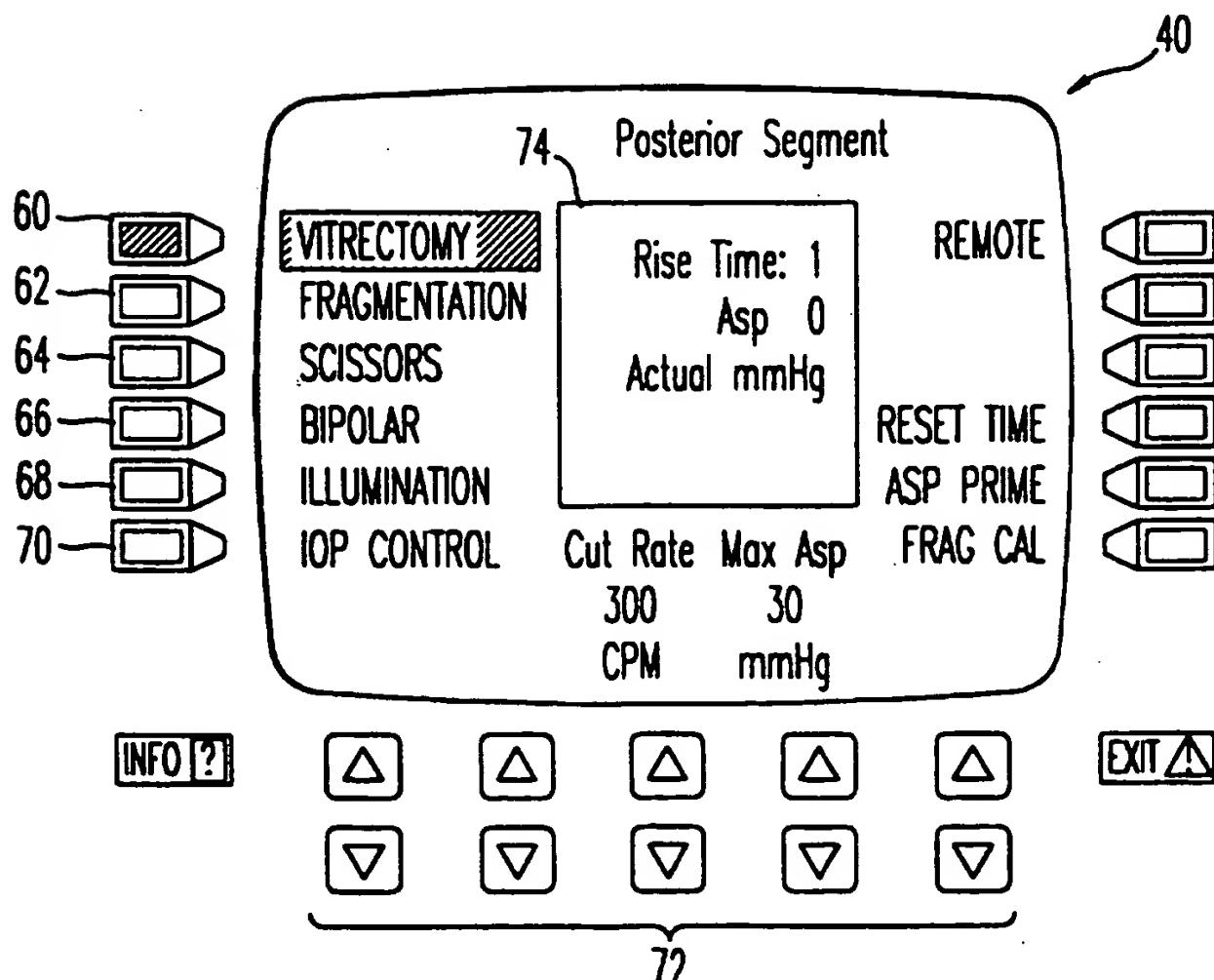


FIG. 2

FIG. 4
PRIOR ART

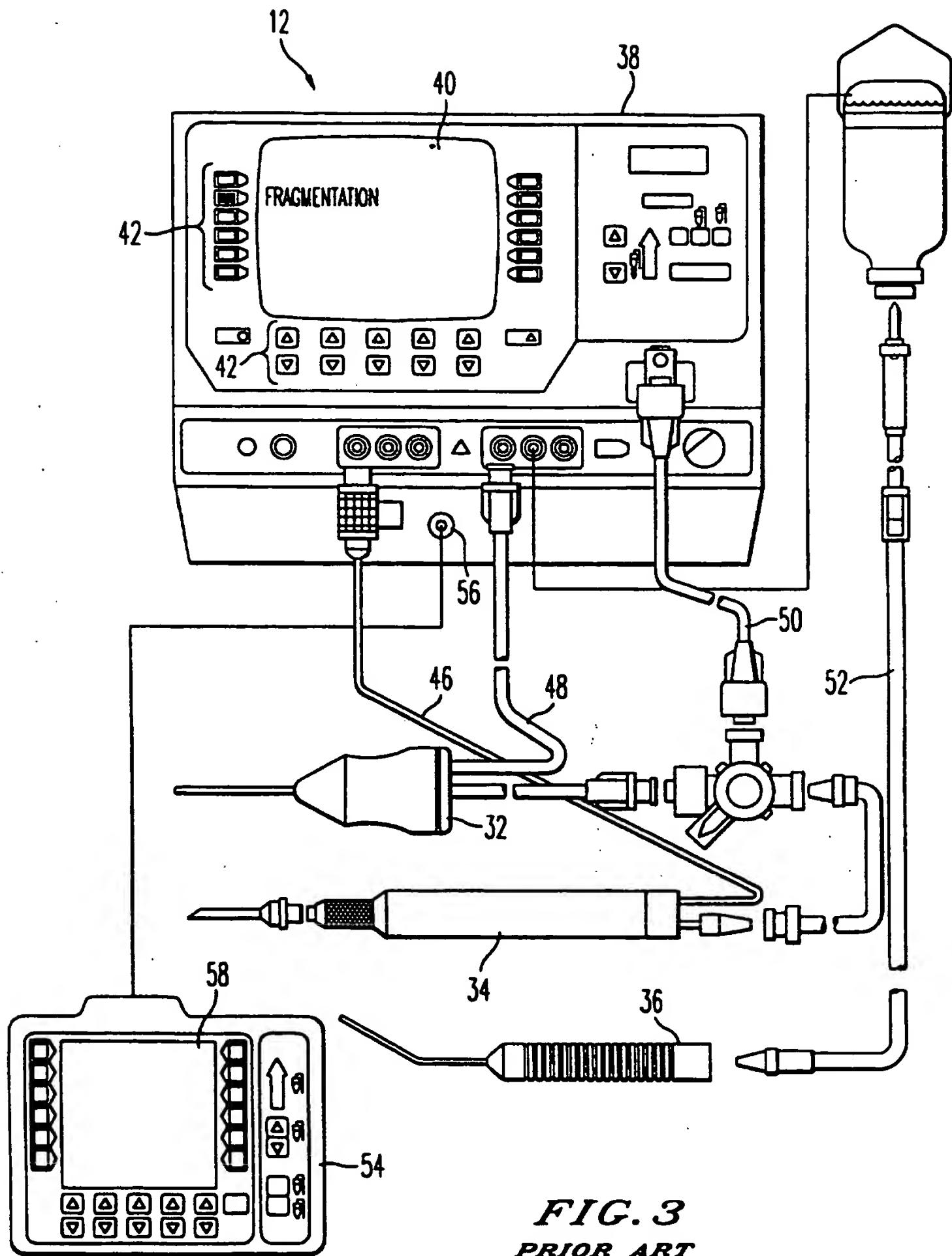
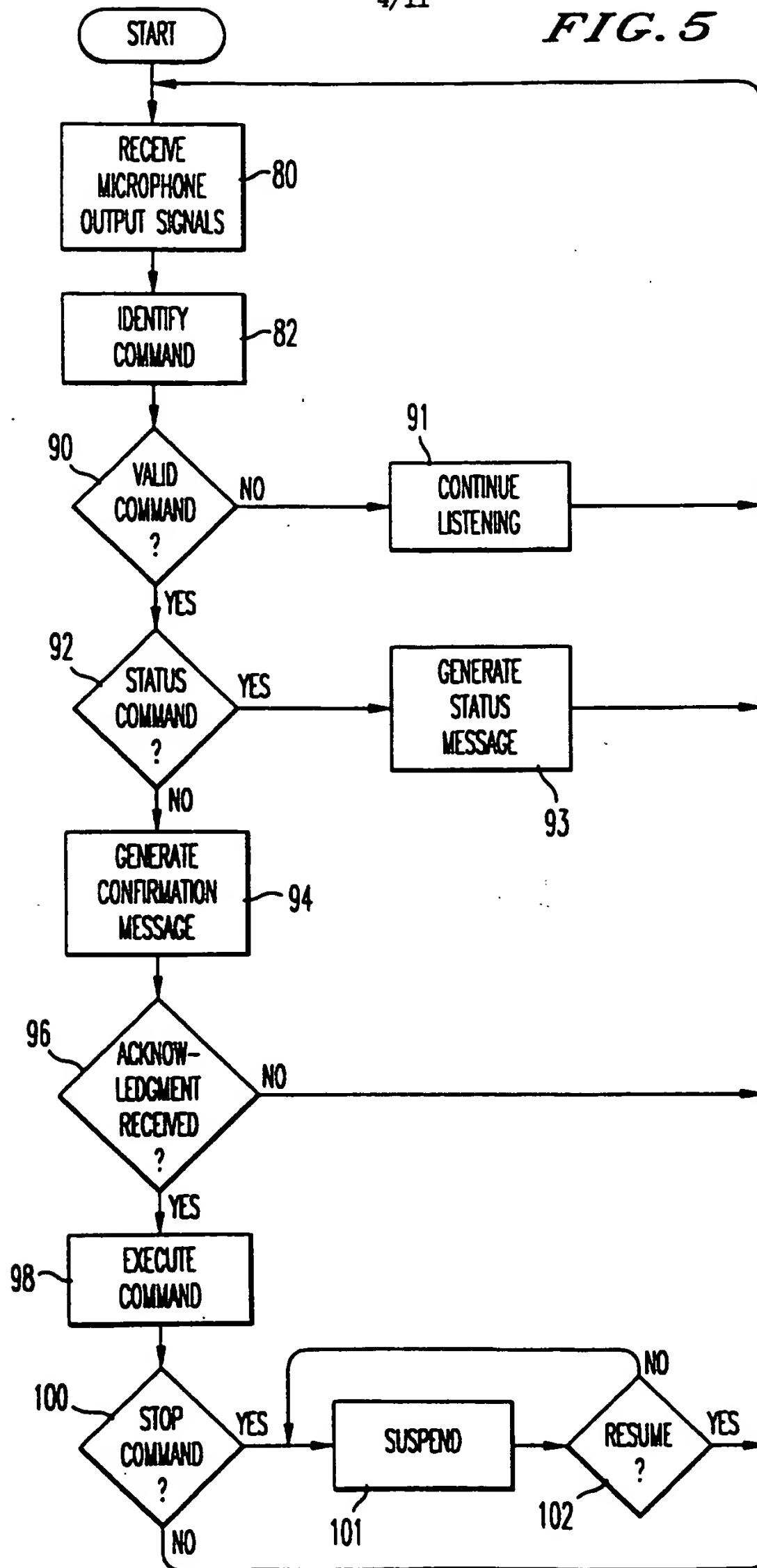


FIG. 3
PRIOR ART

4/11

FIG. 5



5/11

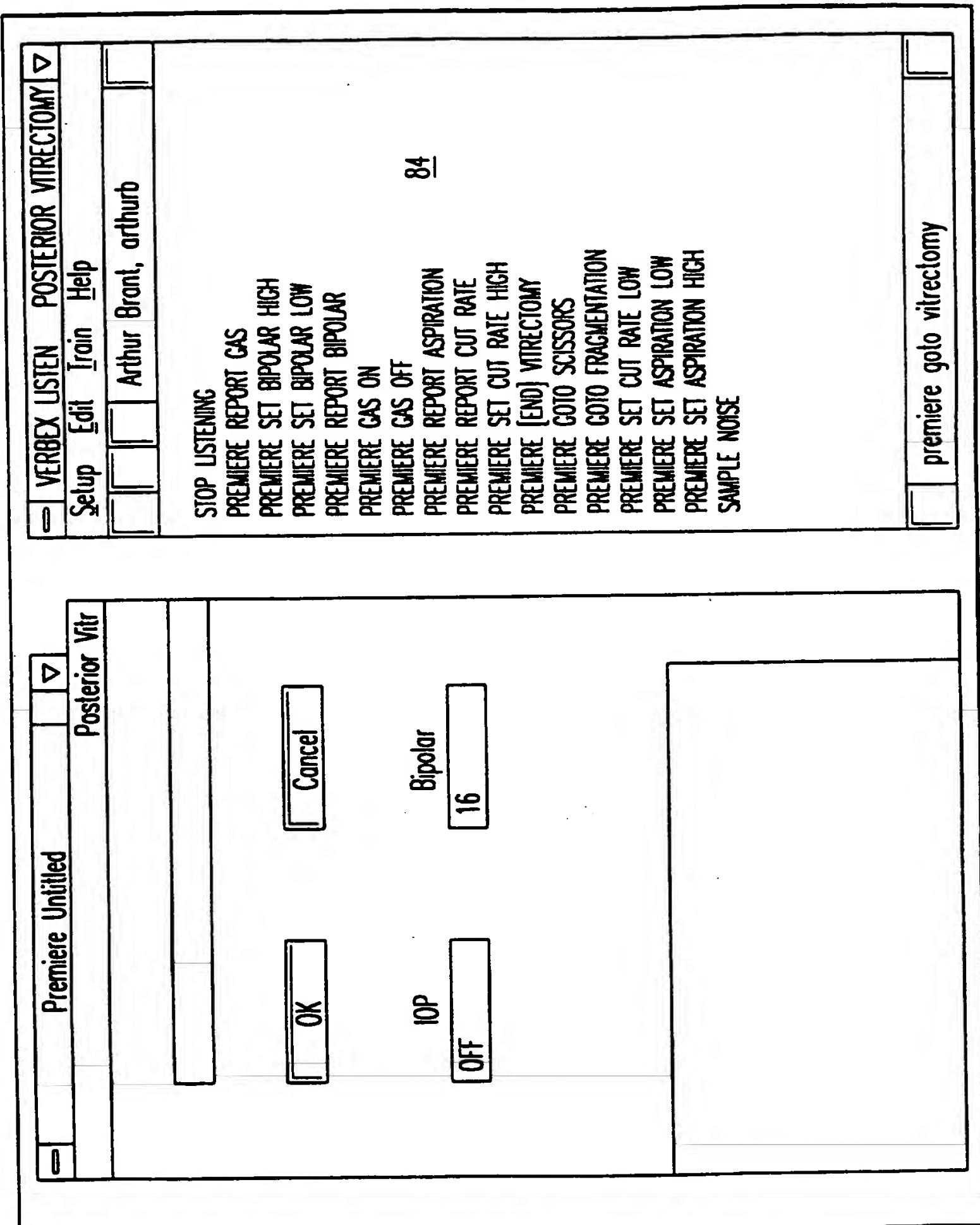


FIG. 6

6/11

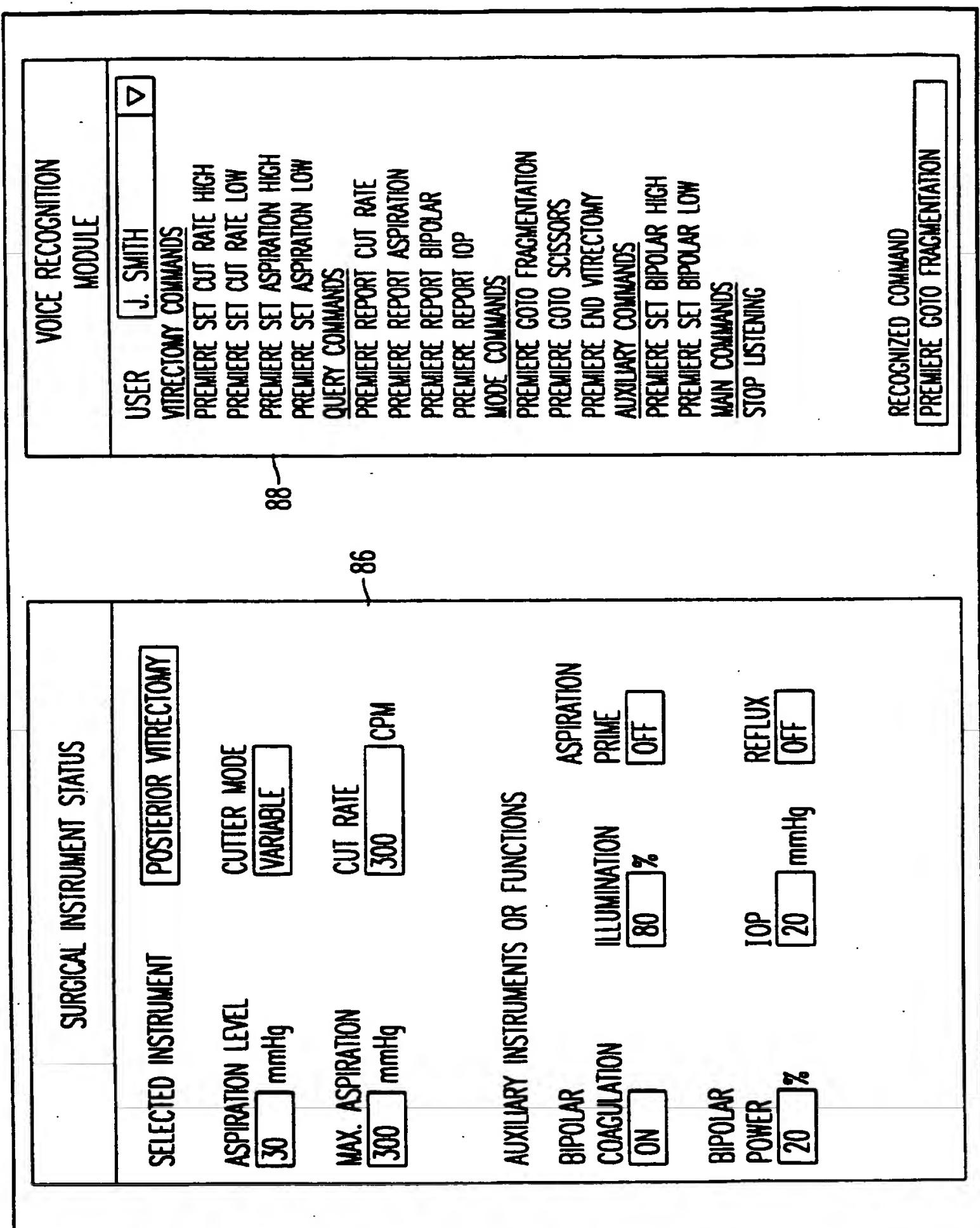


FIG. 7

7/11

VOICE RECOGNITION MODULE	
USER	J. SMITH <input type="checkbox"/>
FRAGMENTATION COMMANDS	
PREMIERE SET POWER HIGH	
PREMIERE SET POWER LOW	
PREMIERE PULSE ON	
PREMIERE PULSE OFF	
PREMIERE SET ASPIRATION HIGH	
PREMIERE SET ASPIRATION LOW	
PREMIERE REPORT POWER	
PREMIERE REPORT PULSE RATE	
PREMIERE REPORT ASPIRATION	
PREMIERE REPORT BIPOLE	
PREMIERE REPORT IOP	
PREMIERE MODE COMMANDS	
PREMIERE GOTO SCISSORS	
PREMIERE GOTO VIBRECTOMY	
PREMIERE END FRAGMENTATION	
AUXILIARY COMMANDS	
PREMIERE SET BIPOLE HIGH PREMIERE SET ILLUM. HIGH	
PREMIERE SET BIPOLE LOW PREMIERE SET ILLUM. LOW	
MAIN COMMANDS	
STOP LISTENING	
RECOGNIZED COMMAND	
PREMIERE SET POWER HIGH	
SELECTED INSTRUMENT	POSTERIOR FRAGMENTATION
ASPIRATION LEVEL	AVERAGE POWER <input type="text"/> 0 %
100 mmHg	ELAPSED TIME <input type="text"/> 1:20 MIN
MAX. ASPIRATION	MAXIMUM POWER <input type="text"/> 5 %
300 mmHg	PULSE RATE <input type="text"/> 100 PPS
SURGICAL INSTRUMENT STATUS	
AUXILIARY INSTRUMENTS OR FUNCTIONS	
BIPOLAR COAGULATION	ASPIRATION PRIME <input type="text"/> OFF
ON <input type="checkbox"/>	ILLUMINATION <input type="text"/> 0 %
BIPOLAR POWER	IOP <input type="text"/> 20 mmHg
60 %	

FIG. 8

8/11

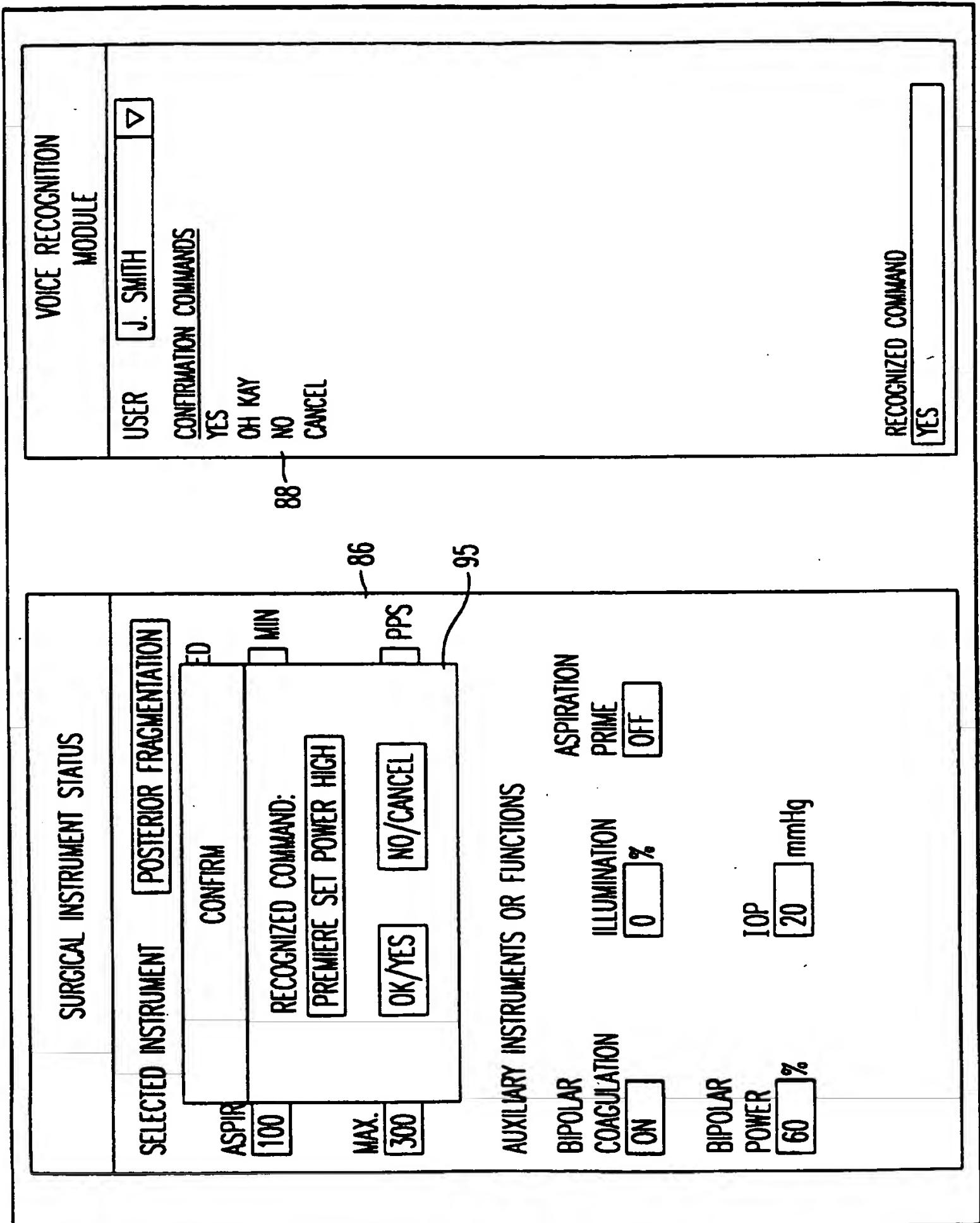


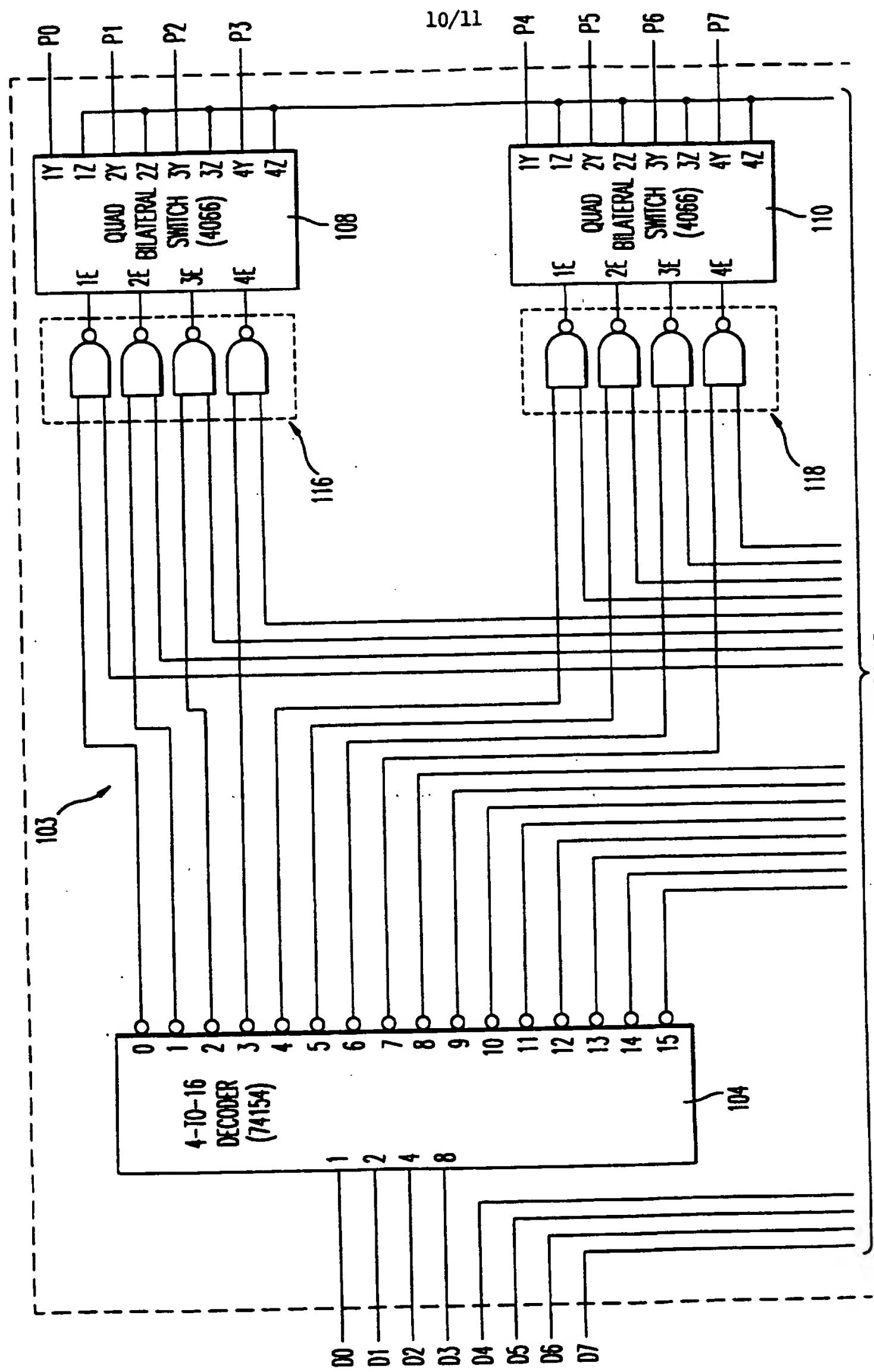
FIG. 9

9/11

VOICE RECOGNITION MODULE	
USER	J. SMITH ▽
FRAGMENTATION COMMANDS	
PREMIERE SET POWER HIGH	
PREMIERE SET POWER LOW	
PREMIERE PULSE ON	
PREMIERE PULSE OFF	
PREMIERE SET ASPIRATION HIGH	
PREMIERE SET ASPIRATION LOW	
QUERY COMMANDS	
PREMIERE REPORT POWER	
PREMIERE REPORT PULSE RATE	
PREMIERE REPORT ASPIRATION	
PREMIERE REPORT BIPOAR	
PREMIERE REPORT IOP	
MODE COMMANDS	
PREMIERE GOTO SCISSORS	
PREMIERE GOTO VRECTOMY	
PREMIERE END FRAGMENTATION	
AUXILIARY COMMANDS	
PREMIERE SET BIPOLAR HIGH	
PREMIERE SET BIPOLAR LOW	
PREMIERE SET ILLUM. HIGH	
PREMIERE SET ILLUM. LOW	
MAIN COMMANDS	
STOP LISTENING	
RECOGNIZED COMMAND	

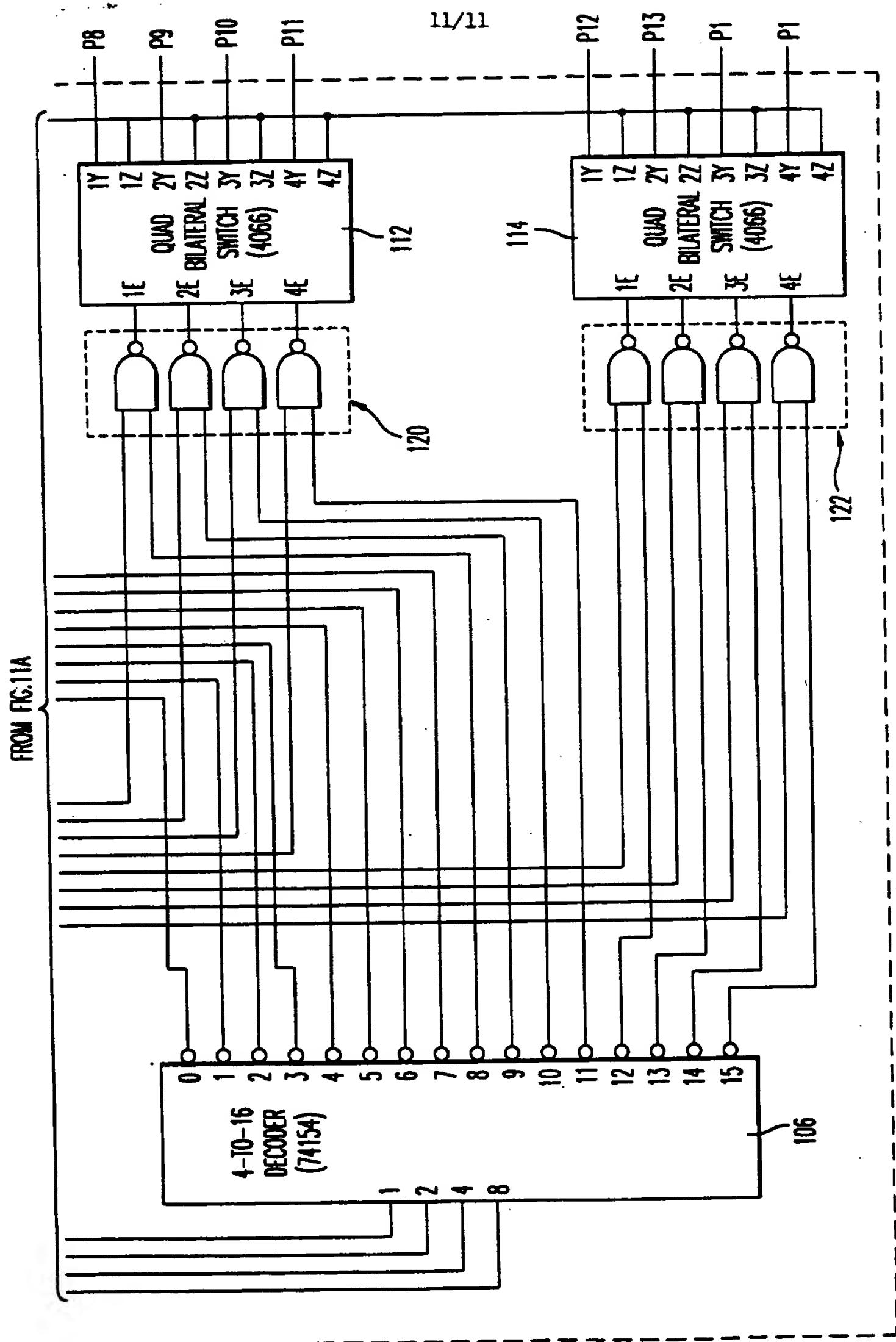
SURGICAL INSTRUMENT STATUS	
SELECTED INSTRUMENT	POSTERIOR FRAGMENTATION
ASPIRATION LEVEL	AVERAGE POWER <input type="text" value="0"/> %
	ELAPSED TIME <input type="text" value="1:20"/> MIN
	PULSE RATE <input type="text" value="100"/> PPS
MAX. ASPIRATION	MAXIMUM POWER <input type="text" value="5"/> %
AUXILIARY INSTRUMENTS OR FUNCTIONS	
BIPOLAR COAGULATION	ASPIRATION PRIME <input type="text" value="OFF"/>
	ILLUMINATION <input type="text" value="0"/> %
BIPOLAR POWER	IOP <input type="text" value="20"/> mmHg
	<input type="text" value="60"/> %

FIG. 10



10 FIG. 11B

FIG. 11A



INTERNATIONAL SEARCH REPORT

International application No.
PCT/US96/17320

A. CLASSIFICATION OF SUBJECT MATTER

IPC(6) : A61B 19/00

US CL : 606/2

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

U.S. : 128/736, 897, 898; 604/19-22; 606/2, 3-52

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 5,181,521 A (LEMELSON) 26 January 1993, entire document.	1-46
---		-----
Y		1-46

 Further documents are listed in the continuation of Box C. See patent family annex.

• Special categories of cited documents:	T	later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
• 'A' document defining the general state of the art which is not considered to be of particular relevance	X	document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
• 'B' earlier document published on or after the international filing date	Y	document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
• 'L' document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reasons (as specified)	A	document member of the same patent family
• 'O' document referring to an oral disclosure, use, exhibition or other means		
• 'P' document published prior to the international filing date but later than the priority date claimed		

Date of the actual completion of the international search
10 FEBRUARY 1997Date of mailing of the international search report
25 FEB 1997Name and mailing address of the ISA/US
Commissioner of Patents and Trademarks
Box PCT
Washington, D.C. 20231
Facsimile No. (703) 305-3590Authorized Officer
DAVID SHAY
Telephone No. (703) 308-2215